# MULTI-INNO TECHNOLOGY CO., LTD.

http://www.multi-inno.com

# **TOUCH PANEL SPECIFICATION**

Model: MI0800CDP-C

#### **Customer:**

Approved	
Commont	

Revision	1.0
Engineering	
Date	2013-07-03
Our Reference	



# **REVISION RECORD**

REV NO.	REV DATE	CONTENTS	REMARKS
1.0	2013-07-03	First Release	



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# ■ APPLICATION

DVD player, UMPC, POS, MID

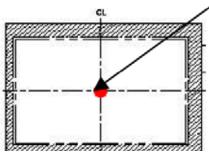
# **■ GENERAL SPECIFICATIONS**

Composition: 8inch Capacitive Touch Panel (CTP). Interface: I<sup>2</sup>C for the CTP.

Item	Specification	Unit
Туре	Transparent type projected capacitive touch panel	
Input mode	Human's finger	
Finger	5	
Resolution	1024x768	dots
Outline Dimension	194.8(W) x 150.4(H) x 1.4(D)	mm
Sensor Active Area	163(W)(typ.) x122.5(H)(typ.)	mm
Transparency	≧85%	%
Haze	≦5.0%	%
Hardness	7H (typ.)[by JIS K5400]	Pencil hardness
Weight	89	g
Report rate	Max : 122	Points/sec
Response time	15	ms
Point hitting life time	1,000,000 times min.	Note 1

Note 1: Use 8 mm diameter silicon rubber/force 3N to knock on the same point twice per second (no-operating), after test function check pass.





# ■ ABSOLUTE MAXIMUM RATINGS

	Symbol	Description	Min	Тур	Max	Unit	Notes
	VCC	Supply voltage	-0.3	-	3.6	V	
I	Vio	DC input voltage	-0.3	-	VCC+0.3	V	



# ■ ELECTRIACL CHARACTERISTICS

Symbol	Description	Min	Тур	Max	Unit	Notes
VCC	Supply voltage	2.6	3.3	3.6	V	
GND	SND Supply voltage		0	-	V	
I	Active Mode	-	10		mA	At VCC=3.3V
Vih	Input H voltage	1.6	-	2.0	V	
VIL	Input L voltage	-	-	0.7	V	
	System clock frequency	-	30	-	MHz	

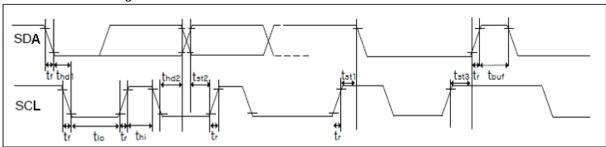
# **■ TIMING SPECIFICATIONS**

# 1. CTP Interface and Data Format [Slave address is 0x5D( 7 bit addressing )]

Communication protocol: I2C

Clock frequency: 100Khz (400Khz Fast mode)

Below is timing of I2C hardware circuit:



Parameter	Symbol	Min	Max	Unit
SCL frequency	f <sub>sck</sub>	-	600	KHZ
SCL low period	t <sub>lo</sub>	0.8	-	us
SCL high period	t <sub>hi</sub>	0.5	-	us
SCL setup time for START condition	t <sub>st1</sub>	0.4	-	us
SCL setup time for STOP condition	t <sub>st3</sub>	0.4	-	us
SCL hold time for START condition	t <sub>st1</sub>	0.4	-	us
SDA setup time	t <sub>st2</sub>	0.5	-	us
SDA hold time	t <sub>st2</sub>	0.2	-	us



#### 2. Timing Characteristic

The address of GT827's slave device is 0xBA/0xBB. When master CPU addressing GT827, it will send read and write control bits simultaneously where are appended to slave device ("0"- write; "1"- read) for composing a byte with device address. i.e.: 0xBA – conduct write operation to GT827; 0xBB – conduct read operation to GT827.

#### 2.1 Postfix Communication:

Only after receiving postfix signal (under the condition of no external signal), can GT827 update coordinate in buffer in real time. After completing communication, I2C needs to send extra postfix signal. But if a series of communication appear, the postfix signal should be sent after the last one finished (except the coordinate reading process, the postfix signal could be sent after finishing reading a frame, so as to prevent output buffer to be changed by GT827 during the read process of master device). Below is the communication format of postfix: Use write process to search register addressing (0x8000), and send stop signal.

#### 2.2 Data Transmission:

The communication usually is launched by master CPU. When SCL keeps "1" SDA manages the change from "1" to "0". Then the address information or data stream begins to transmit after start signal.

Any slave device connected with I2C circuit needs to check 8 bits address information after circuit launches start signal and respond correctly. After receiving the matching address information, GT827 will update SDA as an output and set the value as "0" for answering signal in the ninth clock cycle. The GT827 will lay idle if matching address information is unavailable (neither 0XBA nor 0XBB).

The SDA port sends the data with 9 bits serial data according to nine clock cycles. The 8 valid data + 1 receiver send ACK (acknowledgement signal) or NACK (negative acknowledgement signal). It is valid when SCL is "1" during the data transmission.

The main CPU sends stop signal after transmission where SDA manages the change from "0" to "1" when SCL stays "1".

#### 2.3 Write operations to I<sup>2</sup>C slave



#### Write operations

Above is the flow chart of master CPU conducting write process for GT827. Master CPU launches a start signal and sends address, write and read information ("0" means write process -- 0XBA).

After receiving response, master CPU sends 16 bits address of register and writes 8 bits into register

The address pointer of GT827's register will automatically increase 1 in write process. So it can continuously write continuation register address at a time. If write process is done, master CPU sends stop signal.



#### 2.4 Read operations to I<sup>2</sup>C slave



#### **Read operation**

Above is the flow chart of master CPU conducting read process for GT827. Master CPU launches a start signal and sends address, write and read information ("0" means read process -- 0XAA).

Once receives acknowledgement signal, master CPU sends 16 bits register address information and sets the read-demanding register address. Then master CPU resends a start signal for read process (0XAB). It begins to read data until receiving acknowledge.

Likewise, GT827 can conduct continuation read process. Master CPU will correspondingly send an acknowledgement signal to indicate successful byte reception. And CPU will send "NACK" once receiving the last byte to stop transmission.

3. Register information

Addr	R/W	Name	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0	
0XF40	R	Touch Flags	Buffer Status L_touch P4 P3 P2 P1				P1	P0			
0XF41	R	Touch key	Reserved Key4 Key3 Key2					Key1			
0XF42	R					Point0 X	(H				
0XF43	R	Point0				Point0 >	( L				
0XF44	R	Politio				Point0 Y	′ H				
0XF45	R					Point0 \	/ L				
0XF46	R					Point0 S	ize				
0XF47	R					Point1 X	(H				
0XF48	R	Point1				Point1 >	(L				
0XF49	R	POINT				Point1 Y	′ H				
0XF4A	R					Point1 \	′ L				
0XF4B	R					Point1 S	ize				
0XF4C	R					Point2 X	(H				
0XF4D	R			Point2 X L							
0XF4E	R	Point2		Point2 Y H							
0XF4F	R		Point2 Y L								
0XF50	R					Point2 S	Size				
0XF51	R					Point3 X	(H				
0XF52	R					Point3 >	(L				
0XF53	R	Point3				Point3 Y	′ H				
0XF54	R					Point3 \	′L				
0XF55	R					Point3 S	ize				
0XF56	R					Point4 X	(H				
0XF57	R					Point4 >	( L				
0XF58	R	Point4				Point4 Y	′ H				
0XF59	R					Point4 Y	′L				
0XF5A	R		Point4 Size								
0XF5B	R	Coor checksum			Co	ordinate ch	ecksum				
0XF5C~	_	NC	Pagaryad								
0XF7C	_		Reserved								
0xF7D	R	PID	Product ID(hex)								
0xF7E	R	VID_H			Product	version H	igh byte(h	ex)			



0xF7F         R         VID_L         Product version low byte/fexz)           0xF80         R/W         DriverCH0         Screen 1 drives corresponding IC drive line           0xF81         R/W         DriverCH1         Screen 2 drives corresponding IC drive line           0xF82         R/W         DriverCH3         Screen 4 drives corresponding IC drive line           0xF83         R/W         DriverCH4         Screen 6 drives corresponding IC drive line           0xF84         R/W         DriverCH6         Screen 6 drives corresponding IC drive line           0xF87         R/W         DriverCH6         Screen 6 drives corresponding IC drive line           0xF87         R/W         DriverCH7         Screen 8 drives corresponding IC drive line           0xF88         R/W         DriverCH8         Screen 9 drives corresponding IC drive line           0xF88         R/W         DriverCH8         Screen 10 drives corresponding IC drive line           0xF88         R/W         DriverCH10         Screen 12 drives corresponding IC drive line           0xF80         R/W         DriverCH112         Screen 12 drives corresponding IC drive line           0xF80         R/W         DriverCH13         Screen 13 drives corresponding IC drive line           0xF81         R/W         DriverCH13 <td< th=""><th></th><th></th><th></th><th></th></td<>				
IA/FB1         R/W         DriverCH1         Screen 2 drives corresponding IC drive line           0xF82         R/W         DriverCH2         Screen 3 drives corresponding IC drive line           0xF83         R/W         DriverCH4         Screen 6 drives corresponding IC drive line           0xF85         R/W         DriverCH5         Screen 6 drives corresponding IC drive line           0xF86         R/W         DriverCH6         Screen 6 drives corresponding IC drive line           0xF88         R/W         DriverCH7         Screen 8 drives corresponding IC drive line           0xF88         R/W         DriverCH8         Screen 10 drives corresponding IC drive line           0xF88         R/W         DriverCH9         Screen 11 drives corresponding IC drive line           0xF80         R/W         DriverCH10         Screen 11 drives corresponding IC drive line           0xF80         R/W         DriverCH11         Screen 12 drives corresponding IC drive line           0xF80         R/W         DriverCH13         Screen 13 drives corresponding IC drive line           0xF80         R/W         DriverCH13         Screen 14 drives corresponding IC drive line           0xF81         R/W         DriverCH13         Screen 15 drives corresponding IC drive line           0xF81         R/W         Dri	0xF7F	R	VID_L	Product version low byte(hex)
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0xFAA       R/W       SensorCH12       Screen 13 induction wire corresponds to IC drive line         0xFAB       R/W       SensorCH13       Screen 14 induction wire corresponds to IC drive line         0XFAC       R/W       SensorCH13       Screen 15 induction wire corresponds to IC drive line         0XFAD       R/W       SensorCH14       Screen 16 induction wire corresponds to IC drive line         0XFAE~ 0XFB1       -       NC       Reserved         0xFB2       R/W       ADCCFG       chip scanning control parameter         0xFB3       R/W       SCAN       chip scanning control parameter         0xFB4       R/W       F1SET       drive pulse 1 frequency			SensorCH11	·
0xFAB       R/W       SensorCH13       Screen 14 induction wire corresponds to IC drive line         0XFAC       R/W       SensorCH13       Screen 15 induction wire corresponds to IC drive line         0XFAD       R/W       SensorCH14       Screen 16 induction wire corresponds to IC drive line         0XFAE~ 0XFB1       -       NC       Reserved         0xFB2       R/W       ADCCFG       Chip scanning control parameter         0xFB3       R/W       SCAN       Chip scanning control parameter         0xFB4       R/W       F1SET       drive pulse 1 frequency				·
OXFAC R/W SensorCH13 Screen 15 induction wire corresponds to IC drive line OXFAD R/W SensorCH14 Screen 16 induction wire corresponds to IC drive line OXFAE~ OXFB1 - NC Reserved OXFB2 R/W ADCCFG Chip scanning control parameter OXFB3 R/W SCAN Chip scanning control parameter OXFB4 R/W F1SET drive pulse 1 frequency		_		·
OXFAD     R/W     SensorCH14     Screen 16 induction wire corresponds to IC drive line       0XFAE~ 0XFB1     -     NC     Reserved       0xFB2     R/W     ADCCFG     chip scanning control parameter       0xFB3     R/W     SCAN     chip scanning control parameter       0xFB4     R/W     F1SET     drive pulse 1 frequency				
0XFAE~ 0XFB1     -     NC     Reserved       0xFB2     R/W     ADCCFG     chip scanning control parameter       0xFB3     R/W     SCAN     chip scanning control parameter       0xFB4     R/W     F1SET     drive pulse 1 frequency				
0xFB1     0xFB2     R/W     ADCCFG     chip scanning control parameter       0xFB3     R/W     SCAN     chip scanning control parameter       0xFB4     R/W     F1SET     drive pulse 1 frequency				·
0xFB2     R/W     ADCCFG     chip scanning control parameter       0xFB3     R/W     SCAN     chip scanning control parameter       0xFB4     R/W     F1SET     drive pulse 1 frequency		-	NC	Keserved
0xFB3     R/W     SCAN     chip scanning control parameter       0xFB4     R/W     F1SET     drive pulse 1 frequency		R/W	ADCCFG	chip scanning control parameter
0xFB4 R/W F1SET drive pulse 1 frequency		-		
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0xFB6	R/W	F3SET				drive pulse			су		
0xFB7	R/W	F1PNUM				1 dri					
0xFB8	R/W	F2PNUM				2 dri	ve pu	ılse			
0xFB9	R/W	F3PNUM				3 driv					
0xFBA	R/W	F1DELAY			(	drive pulse	1 ph	ase del	ay		
0xFBB	R/W	F2DELAY		<u>-</u>	C	lrive pulse	2 ph	ase de	lay		
0xFBC	R/W	F3DELAY			(	drive pulse	3 ph	ase del	ay		
0xFBD	R/W	DC-DC				high pres	sure	setting	)		
0xFBE	R/W	Sc_Touch				TP key	thre	shold			
0xFBF	R/W	Sc_Leave				TP key ι	ıp thi	reshold			
0xFC0	R/W	Md_switch	Reserved	DD2: difference And half	Reserved	Shape_E defamation	on	INT pulse mode	SITO denoise switch	Reserved	Reserved
0xFC1	R/W	LPower C	Reserved	time to	low power	consump	tion v	without	pressing: 0-	-63s valid,	unit: S
0xFC2	R/W	Refresh			0-100 valid	d: 0: period	10ms	s. 100:	period 20ms	S	
0xFC3	R/W	Touch_N	Reserve	ed	Reserved				t touch poin		
0xFC4	R/W	Output_Th	output limi	it: output				ation v	alue is highe	er than this	s, 0-254
0xFC5	R/W	X Ou Max H		`							, , ,
0xFC6	R/W	X_Ou_Max_L	1	∧ uirectio	on output m	aximum co	ordina	ate, the	higher byte p	Diaced IIIST	
0xFC7	R/W	Y Ou Max H									
0xFC8	R/W	Y Ou Max L		Y direction	on output ma	aximum co	ordina	ate, the	higher byte p	placed first	
0xFC9	R/W	X Co Sm	Х	direction	slide control	parameter	, 0-25	55 confi	gurable, 0 m	eans closu	re
0xFCA	R/W	Y_Co_Sm	Υ	direction	slide control	parameter	, 0-25	55 confi	gurable, 0 m	eans closu	re
0xFCB	R/W	X_Sp_Lim	coordinate	e)	•				rable, 0 mea		
0xFCC	R/W	Y_Sp_Lim			n speed lim	t of slide: 0	-255	configu	rable, 0 mea	ıns closure	(unit:16
OVECD	R/W		coordinate		ما بالمام ما بالمام		T	مانطيير	noise elimir	antina 0 1	E valid
0xFCD 0xFCE	R/W	Noise_R NC	5	sampling	drop-drive		serve		noise eiimii	iation: 0-1	o valiu
0xFCF	R/W	Filter	Г	Reserved					vy filtorina v	valua (in ha	200 4)
0xFCF 0xFD0	R/W		Г						w filtering v area: 0-255		156 4)
-	-	Large_Tc				-	10				4
0xFD1	R/W	Shake_Cu			nake Count		l nal co	ndition	ger Number ı, 0-255 vali	d 0 means	ount close
0xFD2	R/W	Pos_Ref_T	benchmark	k update	•						
0xFD3	R/W	NC	benchmar close benc			on in sudd	len c	hange	condition,0-	255 valid,	0 means
0xFD4	R/W	NC				Re	serve	h			
0xFD5	R/W	NC				110	501 VC				
0xFD6	R/W	Edge_exp		Reserved	I			0:	weak tensil	le	
	14, 44	Lugo_exp	'	10001 460					1: strong		
0xFD7	R/W	Tc_K_F	Key_co	m	Key_con	Reserve	ed	Vâ	alid interval (unilatera	in regional I): 0-15 val	-
0xFD8	R/W	Key 1		ŀ	(ey 1 positi	on: 0-255 v	valid.	, 0 mea	ns unavailat		
0xFD9	R/W	Key 2									
0xFDA	R/W	Key 3	Key 2 position: 0-255 valid, 0 means unavailable  Key 3 position: 0-255 valid, 0 means unavailable								
0xFDB	R/W	Key 4	Key 4 position: 0-255 valid, 0 means unavailable								
0xFDC	R/W	K_Touch		-	, <sub>1</sub> ,						
0xFDD	R/W	K_Leave	key threshold key up threshold								
0xFDE	R/W	K_SEC_max	au	per limit	of sub-max				lependent k	ey judame	nt
0xFEF	R/W	K DIS min		-					mum in indep		
0xFE0	R/W	X_border_Lim_ Near							proximal bo		

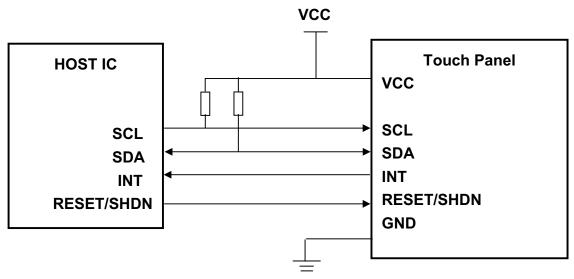
0xFE1	R/W	X_border_Lim_ Far		discarded coordinate numbers on X far end				
0xFE2	R/W	Y_border_Lim_ Near		discarded cod	ordinate num	nbers on Y proximal border		
0xFE3	R/W	Y_border_Lim_ Far		discarded	I coordinate	numbers on Y far end		
0xFE4	R/W	KEY_ADCCFG	FPC	ADCCFG para	meter (appli	cable to drive key common port)		
0xFE5	R/W	KEY_F1SET	FPC	drive frequency	setting (appli	icable to drive key common port)		
0xFE6	R/W	KEY_F1NUM	FPC d	rive pulse numbe	er setting (app	plicable to drive key common port)		
0xFE7	R/W	Key_Shake_Cu		toucl	n key Shake	counter (0-255)		
0xFE8	R/W	Key2_Touch		tou	ch Level of F	FPC touch key2		
0xFE9	R/W	Key3_Touch		tou	ch Level of F	FPC touch key3		
0xFEA	R/W	Key4_Touch		tou	ch Level of F	FPC touch key4		
0xFEB~ 0xFEE	-	NC			Rese	erved		
0xFEF	R/W	Con_Frs	mark for confi information	guration update	, write 1 whe	en master completing configuration		
0xFF0	R/W	Cfg_Chk_H		- <b></b>		lianna dha binbanbada nlasad Sud		
0xFF1	R/W	Cfg_Chk_L	COI	niguration inforr	nation check	ksum, the higher byte placed first		
0xFF2	R/W	System_Sta	Powe	er_sta		Reserved		
0xFF3	R/W	LED_Con	LED_EN	LED_CM	LED_SW	time of light-on after key up (unit: S)		
0xFF4	R/W	Command			Rese	erved		
0xFF5	D /\A/	Modulo Tyro		Doorwood		module supplier' ID:		
UXFFO	R/W	Module_Type		Reserved		0-2 valid		



# **■ PIN CONNECTIONS**

No.	Name	I/O	Description
1	VCC	Р	Power; VCC=3.3V(typ.)
2	SCL	1	Clock; 100KHz
3	SDA	I/O	Serial data access
4	INT	0	Active low when data output from touch panel
5	RESET/SHDN	I	Reset
6	GND	Р	Ground

# ■ BLOCK DIAGRAM



Note: 1. USE APPROPRIATE RESISTOR VALUE DURING HIGH SPEED SCL CLOCK. SUGGESTION: RESISTOR RECOMMENDATION: 1K ohm.

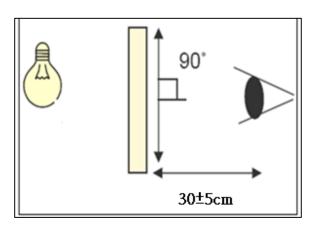
2. To reduce the noise from the power, we suggest you use the independent power for the touch panel (VCC)

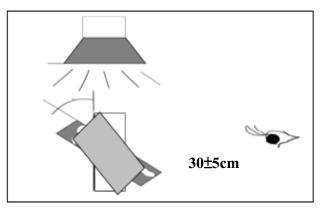


# ■ APPEARANCE SPECIFICATIONS

#### 1.1 Inspection condition

- 1.1.1 Inspection conditions
  - 1.1.1.1 Inspection Distance :  $30 \pm 5$  cm
  - 1.1.1.2 View Angle:
    - (1) Inspection that light pervious to the product: 90±15°
    - (2) Inspection that light reflects on the product: 90±15°





#### 1.1.2 Environment conditions:

Ambient Temperature:	25±5°C
Ambient Humidity:	30~75%RH
Ambient Illumination	600~800 lux

#### 1.2 Inspection Parameters

Appearance inspection standard (D: diameter, L: length; W: width, Z: height, T: glass thickness)

Inspection item	Inspection standard		Description
Foreign material in dot shape	SPEC (unit: mm)	Acceptable	
	D≦0.5	Ignored	OI.
	0.5 <d≦0.8, distance="">5</d≦0.8,>	n≦3	
	D>0.8	0	D= (L + W) / 2
Foreign material in line shape	SPEC	Acceptable	V . V
	W≦0.05 and L≦7	Ignored	L j
	0.05 <w≦0.08, distance="" l≦7,="">5</w≦0.08,>	n≦3	
	W>0.08 or L>7	0	W :
			L : Long W : Width
Contamination	It is acceptable if the dirt can be wiped.		



	0050			
	SPEC	Acceptable		
	W≦0.05 and L≦7			
	0.05 <w≦0.08, distance="" l≦7,="">5 n≦3</w≦0.08,>			
Scratch	0.08 <w≦0.1, distance="" l≦7,="">5</w≦0.1,>	n≦2	L	
	W>0.1 or L>7	0		
Inspection item	SPEC		Description	
	SPEC (unit: mm)	Acceptable		
	D≦0.2	Ignored	0	
	Non visible area	Ignored		
Bubble	0.2 <d≦0.3, distance="">5</d≦0.3,>		D= (L + W) / 2	
	D>0.3 0		0 D-(L+W)/2	
Cover & Sensor Crack	Prohibited		1	
	SPEC (unit: mm)	Acceptable	T T	
	Side/Bottom Ignored			
Cover angle missing	It is prohibited if the defect appears on the front.	0	x z T	
Inspection item	SPEC		Description	
Cover edge break	SPEC (unit: mm)	Acceptable	20 S. IF	
	$X \le 2.0, Y \le 2.0, Z \le T$ Ignored			
	X>2.0, Y>2.0, Z>T	0	T Z	

Sensor angle	SPEC (unit: mm)	Acceptable	\ \ \
missing/edge break	Damage circuit or function.		
	It can be seen from the front of cover visible area.		
Sensor flange	SPEC (unit: mm) Acceptable		
	Do not affect assembly. Ignored		
Ink	SPEC (unit: mm)	Acceptable	
	word unclear, inverted, mistake, break line 0		
Bubble under protection film	SPEC (unit: mm)	Acceptable	
	NA		
Function	Prohibited		

#### 1.3 Sampling Condition

Unless otherwise agree in written, the sampling inspection shall be applied to the incoming inspection of customer.

Lot size: Quantity of shipment lot per model. Sampling type: normal inspection, single sampling Sampling table: MIL-STD-105E

Sampling table: MIL-STD-105E Inspection level: Level II

	Definition		
Class of defects	Major		It is a defect that is likely to result in failure or to reduce materially the usability of the product for the intended function.
	Minor	AQL 1.5%	It is a defect that will not result in functioning problem with deviation classified.

# **■ QUALITY ASSURANCE**

#### 1.1 Test Condition

1.1.1 Temperature and Humidity(Ambient Temperature)

Temperature :  $25 \pm 5^{\circ}$ C Humidity :  $65 \pm 5\%$ 

#### 1.1.2 Operation

Unless specified otherwise, test will be conducted under function state.

#### 1.1.3 Container

Unless specified otherwise, vibration test will be conducted to the product itself without putting it in a container.

# 1.1.4 Test Frequency

In case of related to deterioration such as shock test. It will be conducted only once.

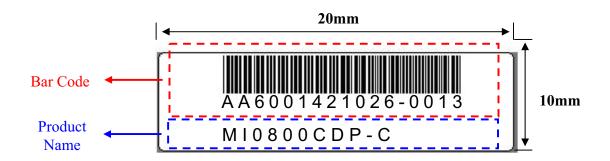
#### 1.1.5 Test Method

	Reliability Test Item & Level	Test Level
No.	Test Item	
1.	High Temperature Storage Test	T= $70^{\circ}$ C, 120hrs after 1 hrs at room temperature and test.
2.	Low Temperature Storage Test	T= -20 $^{\circ}$ C, 120hrs after 1 hrs at room temperature and test.
3.	High Temperature and High Humidity Storage Test	T= 40℃, 90%RH,120hrs after 24 hrs at room temperature and test.
4.	Thermal Cycling Test (No operation)	-20 $^{\circ}$ C 30min ~ 70 $^{\circ}$ C 30 min , 100 Cycles after 24 hrs at room temperature and test.
5.	Vibration Test (No operation)	Frequency :10 ~ 55 HZ Amplitude :1.5 mm Sweep time : 11 mins Test Period: 6 Cycles for each direction of X, Y, Z
6.	ESD TEST	Air Discharge:±15KV Indirect Contact Discharge:±8KV

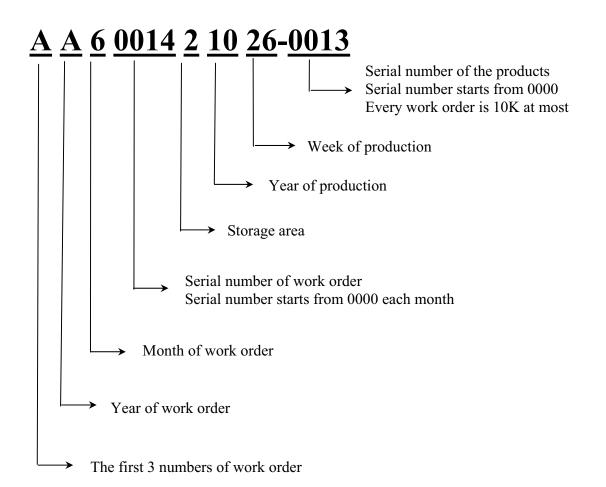


# **■ CTP PRODUCT LABEL DEFINE**

# **CTP Product Label style:**

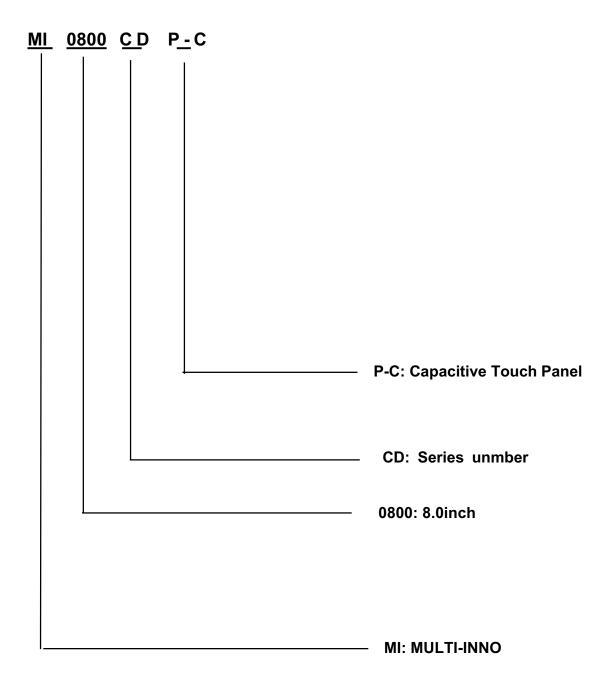


#### **BarCode Define:**





# **Product Name Define:**





#### ■ PRECAUTIONS IN USE CTP

#### 4. ASSEMBLY PRECAUTIONS

- Since Touch Panel is consist of glass, please be careful your hands to be injured during handing. You must wear gloves during handing.
- (2) Do not touch, push or rub the exposed touch panel, tweezers or anything harder than HB pencil lead. And please do not rub with dust clothes with chemical treatment.
- (3) Do not stack the touch panels together. Do not put heavy objects on touch panel.
- (4) Please do not take a CTP to pieces and reconstruct it. Resolving and reconstructing modules may cause them not to work well.
- (5) Please excessive force or strain to the panel or tail is prohibited, Do not lift touch panel by cable(FPC).
- (6) Use clean sacks or glove to prevent fingerprints and/or stains left on the panel. Extra attention and carefulness should be taken while handling the glass edge.
- (7) Please pay attention for the matters stated below at mounting design of touch panel enclosure. Enclosure support to fix touch panel must be out of active area.(do not design enclosure presses the active area to protect from miss put)

#### OPERATING PRECAUTIONS

- Please be sure to turn off the power supply before connecting and disconnecting signal input cable.
- (2) Please do not change variable resistance settings in CTP. They are adjusted to the most suitable value. If they are changed, it might happen CTP does not satisfy the characteristics specification
- (3) Be careful for condensation at sudden temperature change. Condensation makes damage to snesor or electrical contacted parts.
- (4) CTP has high frequency circuits. Sufficient suppression to the electromagnetic interference shall be done by system manufacturers. Grounding and shielding methods may be important to minimize the interference.
- (5) Touch the panel with your finger or stylus only to assure normal operation. Any sharp edged or hard objects are prohibited.
- (6) Operate the panel in a steady environment. Abrupt variation on temperature and humidity may cause malfunction of the panel.

#### 6. ELECTROSTATIC DISCHARGE CONTROL

(1) The operator should be grounded whenever he/she comes into contact with the CTP. Never touch any of the conductive parts such the copper leads on the FPC and the interface terminals with any parts of the human body.

- (2) The CTP should be kept in antistatic bags or other containers resistant to static for storage.
- (3) Only properly grounded soldering irons should be used.
- (4) If an electric screwdriver is used, it should be well grounded and shielded from commutator sparks.
- (5) The normal static prevention measures should be observed for work clothes and working benches; for the latter conductive (rubber) mat is recommended
- (6) Since dry air is inductive to statics, a relative humidity of 50-60% is recommended.

#### STORAGE PRECAUTIONS

- (1) When you store touch panel for a long time, it is recommended to keep the temperature between 0°C-40°C without the exposure of sunlight and to keep the humidity less than 90%RH.
- (2) Please do not leave touch panel in the environment of high humidity and high temperature such as 60°C 90%RH
- (3) Please do not leave touch panel in the environment of low temperature; below -20°C.

#### 2. OTHERS

For the packaging box, please pay attention to the followings:

- a. Please do not pile them up more than 5 boxes. (They are not designed so.) And please do not turn over.
- Please handle packaging box with care not to give them sudden shock and vibrations. And also please do not throw them up.
- c. Packing box and inner case for CTP are made of cardboard. So please pay attention not to get them wet. (Such like keeping them in high humidity or wet place can occur getting them wet.)

#### 3. LIMITED WARRANTY

Unless otherwise agreed between MULTI-INNO and customer, MULTI-INNO will replace or repair any of its CTP which is found to be defective electrically and visually when inspected in accordance with MULTI-INNO acceptance standards, for a period on one year from date of shipment. Confirmation of such date shall be based on freight documents. The warranty liability of MULTI-INNO is limited to repair and/or replacement on the terms set forth above. MULTI-INNO will not responsible for any subsequent or consequential events.



# **■ OUTLINE DRAWING**

