

LCD MODULE SPECIFICATION

Model: DF-SSC0803---M1

This module uses ROHS materials

For customer acceptance

| | omer weekpramer | |
|----------|-----------------|------|
| Customer | | date |
| Approved | | |
| Comments | | |

The standard product specification may change without prior notice in order to improve performance or quality. Please contact Display Future Ltd for updated specification and product status before design for the standard product or release of the order.

| Revision | 1.0 |
|---------------|-----------|
| Engineering | |
| Date | 2018/01/4 |
| Our Reference | |

REVISION RECORD

| REV NO. | REV DATE | CONTENTS | REMARKS |
|---------|-----------|---------------|---------|
| 1.0 | 2018-01-4 | First Release | |
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■ APPLICATION

DVD player, UMPC, POS, MID

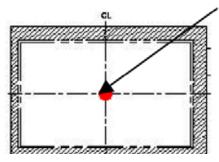
■ GENERAL SPECIFICATIONS

Composition: 8inch Capacitive Touch Panel (CTP). Interface: I^2C for the CTP.

| Item | Specification | Unit |
|-------------------------|---|-----------------|
| Туре | Transparent type projected capacitive touch panel | |
| Input mode | Human's finger | |
| Finger | 5 | |
| Resolution | 1024x768 | dots |
| Outline Dimension | 194.8(W) x 150.4(H) x 1.4(D) | mm |
| Sensor Active Area | 163(W)(typ.) x122.5(H)(typ.) | mm |
| Transparency | ≧85% | % |
| Haze | ≦5.0% | % |
| Hardness | 7H (typ.)[by JIS K5400] | Pencil hardness |
| Weight | 89 | g |
| Report rate | Max : 122 | Points/sec |
| Response time | 15 | ms |
| Point hitting life time | 1,000,000 times min. | Note 1 |

Note 1: Use 8 mm diameter silicon rubber/force 3N to knock on the same point twice per second (no-operating), after test function check pass.





■ ABSOLUTE MAXIMUM RATINGS

| Symbol | Description | Min | Тур | Max | Unit | Notes |
|--------|------------------|------|-----|---------|------|-------|
| VCC | Supply voltage | -0.3 | - | 3.6 | V | |
| Vio | DC input voltage | -0.3 | - | VCC+0.3 | V | |

■ ELECTRIACL CHARACTERISTICS

| Symbol | Description | Min | Тур | Max | Unit | Notes |
|--------|------------------------|-----|-----|-----|------|-------------|
| VCC | Supply voltage | 2.6 | 3.3 | 3.6 | V | |
| GND | Supply voltage | - | 0 | - | V | |
| I | Active Mode | - | 10 | | mA | At VCC=3.3V |
| Vih | Input H voltage | 1.6 | - | 2.0 | V | |
| VIL | Input L voltage | - | - | 0.7 | V | |
| | System clock frequency | - | 30 | - | MHz | |

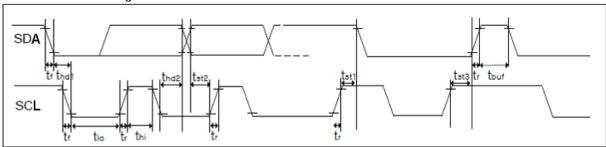
■ TIMING SPECIFICATIONS

1. CTP Interface and Data Format [Slave address is 0x5D(7 bit addressing)]

Communication protocol: I2C

Clock frequency: 100Khz (400Khz Fast mode)

Below is timing of I2C hardware circuit:



| Parameter | Symbol | Min | Max | Unit |
|------------------------------------|------------------|-----|-----|------|
| SCL frequency | f _{sck} | - | 600 | KHZ |
| SCL low period | t _{lo} | 0.8 | - | us |
| SCL high period | t _{hi} | 0.5 | - | us |
| SCL setup time for START condition | t _{st1} | 0.4 | - | us |
| SCL setup time for STOP condition | t _{st3} | 0.4 | - | us |
| SCL hold time for START condition | t _{st1} | 0.4 | - | us |
| SDA setup time | t _{st2} | 0.5 | - | us |
| SDA hold time | t _{st2} | 0.2 | - | us |

2. Timing Characteristic

The address of GT827's slave device is 0xBA/0xBB. When master CPU addressing GT827, it will send read and write control bits simultaneously where are appended to slave device ("0"- write; "1"- read) for composing a byte with device address. i.e.: 0xBA – conduct write operation to GT827; 0xBB – conduct read operation to GT827.

2.1 Postfix Communication:

Only after receiving postfix signal (under the condition of no external signal), can GT827 update coordinate in buffer in real time. After completing communication, I2C needs to send extra postfix signal. But if a series of communication appear, the postfix signal should be sent after the last one finished (except the coordinate reading process, the postfix signal could be sent after finishing reading a frame, so as to prevent output buffer to be changed by GT827 during the read process of master device). Below is the communication format of postfix: Use write process to search register addressing (0x8000), and send stop signal.

2.2 Data Transmission:

The communication usually is launched by master CPU. When SCL keeps "1" SDA manages the change from "1" to "0". Then the address information or data stream begins to transmit after start signal.

Any slave device connected with I2C circuit needs to check 8 bits address information after circuit launches start signal and respond correctly. After receiving the matching address information, GT827 will update SDA as an output and set the value as "0" for answering signal in the ninth clock cycle. The GT827 will lay idle if matching address information is unavailable (neither 0XBA nor 0XBB).

The SDA port sends the data with 9 bits serial data according to nine clock cycles. The 8 valid data + 1 receiver send ACK (acknowledgement signal) or NACK (negative acknowledgement signal). It is valid when SCL is "1" during the data transmission.

The main CPU sends stop signal after transmission where SDA manages the change from "0" to "1" when SCL stays "1".

2.3 Write operations to I²C slave



Write operations

Above is the flow chart of master CPU conducting write process for GT827. Master CPU launches a start signal and sends address, write and read information ("0" means write process -- 0XBA).

After receiving response, master CPU sends 16 bits address of register and writes 8 bits into register

The address pointer of GT827's register will automatically increase 1 in write process. So it can continuously write continuation register address at a time. If write process is done, master CPU sends stop signal.

2.4 Read operations to I²C slave



Read operation

Above is the flow chart of master CPU conducting read process for GT827. Master CPU launches a start signal and sends address, write and read information ("0" means read process -- 0XAA).

Once receives acknowledgement signal, master CPU sends 16 bits register address information and sets the read-demanding register address. Then master CPU resends a start signal for read process (0XAB). It begins to read data until receiving acknowledge.

Likewise, GT827 can conduct continuation read process. Master CPU will correspondingly send an acknowledgement signal to indicate successful byte reception. And CPU will send "NACK" once receiving the last byte to stop transmission.

3. Register information

| Addr | R/W | Name | bit7 | bit6 | bit5 | bit4 | bit3 | bit2 | bit1 | bit0 | | |
|-----------------|-----|---------------|--------------------------------|----------------------------|------|-------------|--------|------|------|------|--|--|
| 0XF40 | R | Touch Flags | Buffer Status L_touch P4 P3 P2 | | | | | P1 | P0 | | | |
| 0XF41 | R | Touch key | | Reserved Key4 Key3 Key2 Ke | | | | | | Key1 | | |
| 0XF42 | R | | | | | Point0 > | (H | | | | | |
| 0XF43 | R | Point0 | | | | Point0) | (L | | | | | |
| 0XF44 | R | Foilito | | | | Point0 \ | ′ H | | | | | |
| 0XF45 | R | | | | | Point0 \ | / L | | | | | |
| 0XF46 | R | | | | | Point0 S | ize | | | | | |
| 0XF47 | R | | | | | Point1 > | (H | | | | | |
| 0XF48 | R | Point1 | | | | Point1 > | (L | | | | | |
| 0XF49 | R | TOILL | | | | Point1 Y | ′ H | | | | | |
| 0XF4A | R | | | | | Point1 \ | ′L | | | | | |
| 0XF4B | R | | | | | Point1 S | | | | | | |
| 0XF4C | R | | | | | Point2 X | (H | | | | | |
| 0XF4D | R | | Point2 X L | | | | | | | | | |
| 0XF4E | R | Point2 | Point2 Y H | | | | | | | | | |
| 0XF4F | R | | Point2 Y L | | | | | | | | | |
| 0XF50 | R | | Point2 Size | | | | | | | | | |
| 0XF51 | R | | | | | Point3 X | (H | | | | | |
| 0XF52 | R | | | | | Point3 > | (L | (L | | | | |
| 0XF53 | R | Point3 | | | | Point3 Y | ′ H | | | | | |
| 0XF54 | R | | | | | Point3 \ | | | | | | |
| 0XF55 | R | | | | | Point3 S | ize | | | | | |
| 0XF56 | R | | | | | Point4 > | (H | | | | | |
| 0XF57 | R | | Point4 X L | | | | | | | | | |
| 0XF58 | R | Point4 | Point4 Y H | | | | | | | | | |
| 0XF59 | R | | | | | Point4 \ | | | | | | |
| 0XF5A | R | | Point4 Size | | | | | | | | | |
| 0XF5B | R | Coor checksum | | | Co | ordinate ch | ecksum | | | | | |
| 0XF5C~ 0XF7C | - | NC | Reserved | | | | | | | | | |
| 0xF7D | R | PID | | | | Product ID | (hex) | | | | | |
| 0xF7E | R | VID_H | | | | version H | , , | ex) | | | | |

| 0xF7F | Р | VID I | Draduat varaion law hyta/hav |
|----------------|-------|----------------|---|
| | R | VID_L | Product version low byte(hex) |
| 0xF80 | R/W | DriverCH0 | Screen 1 drives corresponding IC drive line |
| 0xF81 | R/W | DriverCH1 | Screen 2 drives corresponding IC drive line |
| 0xF82 | R/W | DriverCH2 | Screen 3 drives corresponding IC drive line |
| 0xF83 | R/W | DriverCH3 | Screen 4 drives corresponding IC drive line |
| 0xF84 | R/W | DriverCH4 | Screen 5 drives corresponding IC drive line |
| 0xF85 | R/W | DriverCH5 | Screen 6 drives corresponding IC drive line |
| 0xF86 | R/W | DriverCH6 | Screen 7 drives corresponding IC drive line |
| 0xF87 | R/W | DriverCH7 | Screen 8 drives corresponding IC drive line |
| 0xF88 | R/W | DriverCH8 | Screen 9 drives corresponding IC drive line |
| 0xF89 | R/W | DriverCH9 | Screen 10 drives corresponding IC drive line |
| 0xF8A | R/W | DriverCH10 | Screen 11 drives corresponding IC drive line |
| 0xF8B | R/W | DriverCH11 | Screen 12 drives corresponding IC drive line |
| 0xF8C | R/W | DriverCH12 | Screen 13 drives corresponding IC drive line |
| 0xF8D | R/W | DriverCH13 | Screen 14 drives corresponding IC drive line |
| 0xF8E | R/W | DriverCH14 | Screen 15 drives corresponding IC drive line |
| 0xF8F | R/W | DriverCH15 | Screen 16 drives corresponding IC drive line |
| 0xF90 | R/W | DriverCH16 | Screen 17 drives corresponding IC drive line |
| 0xF91 | R/W | DriverCH17 | Screen 18 drives corresponding IC drive line |
| 0xF92 | R/W | DriverCH18 | Screen 19 drives corresponding IC drive line |
| 0xF93 | R/W | DriverCH19 | Screen 20 drives corresponding IC drive line |
| 0xF94 | R/W | DriverCH20 | Screen 21 drives corresponding IC drive line |
| 0xF95 | R/W | DriverCH21 | Screen 22 drives corresponding IC drive line |
| 0xF96 | R/W | DriverCH22 | Screen 23 drives corresponding IC drive line |
| 0xF97 | R/W | DriverCH23 | Screen 24 drives corresponding IC drive line |
| 0xF98 | R/W | DriverCH24 | Screen 25 drives corresponding IC drive line |
| 0xF99 | R/W | DriverCH25 | Screen 26 drives corresponding IC drive line |
| 0xF9A | R/W | DriverCH26 | Screen 27 drives corresponding IC drive line |
| 0xF9B | R/W | DriverCH27 | Screen 28 drives corresponding IC drive line |
| 0xF9C | R/W | DriverCH28 | Screen 29 drives corresponding IC drive line |
| 0xF9D | R/W | NC | Reserved |
| 0xF9E | R/W | SensorCH0 | Screen 1 induction wire corresponds to IC drive line |
| 0xF9F | R/W | SensorCH1 | Screen 2 induction wire corresponds to IC drive line |
| 0xFA0 | R/W | SensorCH2 | Screen 3 induction wire corresponds to IC drive line |
| 0xFA1 | R/W | SensorCH3 | Screen 4 induction wire corresponds to IC drive line |
| 0xFA2 | R/W | SensorCH4 | Screen 5 induction wire corresponds to IC drive line |
| 0xFA3 | R/W | SensorCH5 | Screen 6 induction wire corresponds to IC drive line |
| 0xFA4 | R/W | SensorCH6 | Screen 7 induction wire corresponds to IC drive line |
| 0xFA5 | R/W | SensorCH7 | Screen 8 induction wire corresponds to IC drive line |
| 0xFA6 | R/W | SensorCH8 | Screen 9 induction wire corresponds to IC drive line |
| 0xFA7 | R/W | SensorCH9 | Screen 10 induction wire corresponds to IC drive line |
| 0xFA8 | R/W | SensorCH10 | Screen 11 induction wire corresponds to IC drive line |
| 0xFA9 | R/W | SensorCH11 | Screen 12 induction wire corresponds to IC drive line |
| 0xFAA | R/W | SensorCH12 | Screen 13 induction wire corresponds to IC drive line |
| 0xFAB | R/W | SensorCH13 | Screen 14 induction wire corresponds to IC drive line |
| 0XFAC | R/W | SensorCH13 | Screen 15 induction wire corresponds to IC drive line |
| 0XFAD | R/W | SensorCH14 | Screen 16 induction wire corresponds to IC drive line |
| 0XFAE~ | 14 44 | | |
| 0XFB1 | - | NC | Reserved |
| 0xFB2 | R/W | ADCCFG | chip scanning control parameter |
| 0xFB2 | R/W | SCAN | chip scanning control parameter |
| 0xFB3 0xFB4 | R/W | F1SET | drive pulse 1 frequency |
| 0xFB4 0xFB5 | R/W | F1SET F2SET | drive pulse 1 frequency drive pulse 2 frequency |
| UXFBO | K/ VV | FZSET | drive pulse 2 frequency |

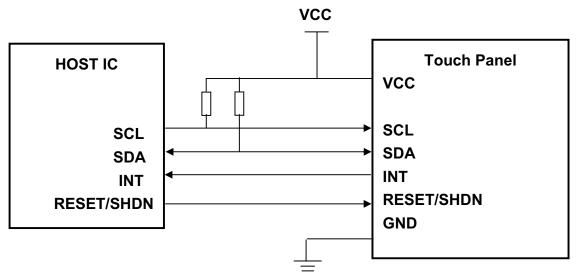
| 0xFB6 | R/W | F3SET | drive pulse 3 frequency | | | | | | | | |
|-------|-----|-----------------------|-------------------------|--------------------------------|---------------|-------------------------|--------------|----------------------|--------------------------------|-----------------------------|------------|
| 0xFB7 | R/W | F1PNUM | | 1 drive pulse | | | | | | | |
| 0xFB8 | R/W | F2PNUM | | 2 drive pulse | | | | | | | |
| 0xFB9 | R/W | F3PNUM | | | | 3 d | rive p | uilse | | | |
| 0xFBA | R/W | F1DELAY | | | d | rive puls | se 1 pł | nase del | ay | | |
| 0xFBB | R/W | F2DELAY | | | | rive puls | | | | | |
| 0xFBC | R/W | F3DELAY | | | | rive puls | | | • | | |
| 0xFBD | R/W | DC-DC | | | | | | e setting | _ | | |
| 0xFBE | R/W | Sc Touch | | | | | | eshold | | | |
| 0xFBF | R/W | Sc Leave | | | | | - | reshold | | | |
| 0xFC0 | R/W | Md_switch | Reserved | DD2: difference And half | Reserved | Shape defama deno | ation ise | INT pulse mode | SITO denoise switch | Reserved | Reserved |
| 0xFC1 | R/W | LPower_C | Reserved | time to | low power | consum | ption | without | pressing: 0- | -63s valid, | unit: S |
| 0xFC2 | R/W | Refresh | | | 0-100 valid | ; 0: perio | od 10m | ns, 100: | period 20ms | 3 | |
| 0xFC3 | R/W | Touch_N | Reserv | /ed | Reserved | | | Outpu | t touch poin | t, 1-5 valid | |
| 0xFC4 | R/W | Output_Th | | | | | | | alue is highe sing coordin | | |
| 0xFC5 | R/W | X_Ou_Max_H | | X directio | n Authut ma | ximum c | coordin | ate the | higher byte p | laced firet | |
| 0xFC6 | R/W | X_Ou_Max_L | | A dilectio | ii output me | MITIUITIC | Joordin | iale, li ie | riigi iei byte p | naceu ili si | |
| 0xFC7 | R/W | Y_Ou_Max_H | | V directio | o output ma | vimum o | oordin | ata tha | higher byte r | lacad first | |
| 0xFC8 | R/W | Y_Ou_Max_L | | r directio | i output ma | XIIIUIII C | COOLUIT | iate, trie | higher byte p | naceu iiisi | |
| 0xFC9 | R/W | X_Co_Sm | × | direction s | lide control | paramet | er, 0-2 | 55 confi | gurable, 0 m | eans closu | re |
| 0xFCA | R/W | Y_Co_Sm | Y | direction s | lide control | paramet | er, 0-2 | 55 confi | gurable, 0 m | eans closu | re |
| 0xFCB | R/W | X_Sp_Lim | X direction | | speed limit | of slide: | 0-255 | configu | ırable, 0 mea | ns closure(| (unit:16 |
| 0xFCC | R/W | Y_Sp_Lim | Y direction coordinate | | speed limit | of slide: | 0-255 | configu | ırable, 0 mea | ns closure(| unit:16 |
| 0xFCD | R/W | Noise_R | | sampling of | drop-driven | | | while | noise elimir | nation: 0-1 | 5 valid |
| 0xFCE | R/W | NC | | | | R | Reserv | ed | | | |
| 0xFCF | R/W | Filter | | Reserved | | coc | ordinat | e windo | w filtering v | alue (in ba | ise 4) |
| 0xFD0 | R/W | Large_Tc | | repre | esentative t | ouch po | oints fo | or large | area: 0-255 | valid | |
| 0xFD1 | R/W | Shake_Cu | | | ake Count | | | | ger Number | | |
| 0xFD2 | R/W | Pos_Ref_T | benchma | rk update | _ | | | | i, 0-255 valid | | |
| 0xFD3 | R/W | NC | | irk update chmark up | | on in suc | dden d | change | condition,0- | 255 valid, | 0 means |
| 0xFD4 | R/W | NC NC | | | | R | Reserv | ed | | | |
| 0xFD5 | R/W | NC | | | | | | | 1 | | |
| 0xFD6 | R/W | Edge_exp | | Reserved | | | | 0: | weak tensil 1: strong | e | |
| 0xFD7 | R/W | Tc_K_F | Key_c | om K | ey_con | Reser | ved | Vā | alid interval i (unilateral | in regional l): 0-15 val | • |
| 0xFD8 | R/W | Key 1 | | K | ey 1 position | n: 0-25 | 5 valid | l, 0 mea | ans unavailab | | |
| 0xFD9 | R/W | Key 2 | | | | | | | ans unavailab | | |
| 0xFDA | R/W | Key 3 | | | | | | | ans unavailab | | |
| 0xFDB | R/W | Key 4 | | | <u> </u> | | | | ans unavailab | | |
| 0xFDC | R/W | K Touch | | | - | | thres | | | | |
| 0xFDD | R/W | K_Leave | | | | | up thre | | | | |
| 0xFDE | R/W | K_SEC_max | u | pper limit o | of sub-max | | | | dependent k | ey judame | nt |
| 0xFEF | R/W | K_DIS_min | | - | | | | | mum in indep | | |
| 0xFE0 | R/W | X_border_Lim_ Near | | | | | | | proximal bo | | - ~ |
| | | | | | | | | | | | |

| 0xFE1 | R/W | X_border_Lim_ Far | | discarded coordinate numbers on X far end | | | | |
|-----------------|--------|-----------------------|-------------------------------|---|-----------------|----------|---------------------------------------|--|
| 0xFE2 | R/W | Y_border_Lim_ Near | | discarded cod | ordinate num | nbers or | n Y proximal border | |
| 0xFE3 | R/W | Y_border_Lim_ Far | | discarded | l coordinate | numbe | rs on Y far end | |
| 0xFE4 | R/W | KEY_ADCCFG | FPC | ADCCFG para | meter (appli | cable to | drive key common port) | |
| 0xFE5 | R/W | KEY_F1SET | FPC | drive frequency | setting (appli | cable to | o drive key common port) | |
| 0xFE6 | R/W | KEY_F1NUM | FPC d | rive pulse numbe | er setting (app | olicable | to drive key common port) | |
| 0xFE7 | R/W | Key_Shake_Cu | | touch key Shake counter (0-255) | | | | |
| 0xFE8 | R/W | Key2_Touch | | tou | ch Level of F | PC tou | ıch key2 | |
| 0xFE9 | R/W | Key3_Touch | | tou | ch Level of F | PC tou | ıch key3 | |
| 0xFEA | R/W | Key4_Touch | | tou | ch Level of F | PC tou | ıch key4 | |
| 0xFEB~ 0xFEE | - | NC | | | Rese | erved | | |
| 0xFEF | R/W | Con_Frs | mark for confi information | guration update | , write 1 whe | en mast | er completing configuration | |
| 0xFF0 | R/W | Cfg_Chk_H | | . | | | a a biaban buta alaa ad Saat | |
| 0xFF1 | R/W | Cfg_Chk_L | cor | iliguration inforr | nation check | ksum, tr | ne higher byte placed first | |
| 0xFF2 | R/W | System_Sta | Powe | er_sta | | | Reserved | |
| 0xFF3 | R/W | LED_Con | LED_EN | LED_CM | LED_SW | tin | ne of light-on after key up (unit: S) | |
| 0xFF4 | R/W | Command | | | Rese | rved | | |
| 0xFF5 | D /\A/ | Madula Tura | 5 . | | | | module supplier' ID: | |
| UXFF3 | R/W | Module_Type | | Reserved | | | 0-2 valid | |

■ PIN CONNECTIONS

| No. | Name | I/O | Description |
|-----|------------|-----|--|
| 1 | VCC | Р | Power; VCC=3.3V(typ.) |
| 2 | SCL | I | Clock; 100KHz |
| 3 | SDA | I/O | Serial data access |
| 4 | INT | 0 | Active low when data output from touch panel |
| 5 | RESET/SHDN | I | Reset |
| 6 | GND | Р | Ground |

■ BLOCK DIAGRAM



Note: 1. USE APPROPRIATE RESISTOR VALUE DURING HIGH SPEED SCL CLOCK. SUGGESTION: RESISTOR RECOMMENDATION: 1K ohm.

2. To reduce the noise from the power, we suggest you use the independent power for the touch panel (VCC)

■ APPEARANCE SPECIFICATIONS

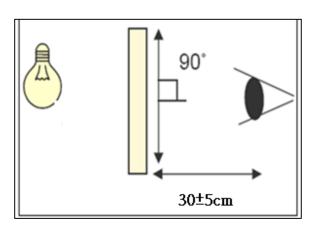
1.1 Inspection condition

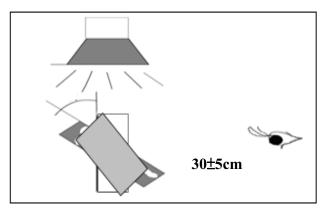
1.1.1 Inspection conditions

1.1.1.1 Inspection Distance : 30 ± 5 cm

1.1.1.2 View Angle:

- (1) Inspection that light pervious to the product: 90±15°
- (2) Inspection that light reflects on the product: 90±15°





1.1.2 Environment conditions:

| Ambient Temperature: | 25±5°C |
|----------------------|-------------|
| Ambient Humidity: | 30~75%RH |
| Ambient Illumination | 600~800 lux |

1.2 Inspection Parameters

Appearance inspection standard (D: diameter, L: length; W: width, Z: height, T: glass thickness)

| Inspection item | Inspection standard | Description | |
|-----------------------------------|---|-------------|--------------------|
| Foreign material in dot shape | SPEC (unit: mm) | Acceptable | |
| | D≦0.5 | Ignored | OI. |
| | 0.5 <d≦0.8, distance="">5</d≦0.8,> | n≦3 | |
| | D>0.8 | 0 | D= (L + W) / 2 |
| Foreign material in line shape | SPEC | Acceptable | V . V |
| | W≦0.05 and L≦7 | Ignored | Į L j |
| | 0.05 <w≦0.08, distance="" l≦7,="">5</w≦0.08,> | n≦3 | |
| | W>0.08 or L>7 | 0 | W |
| | | | L : Long W : Width |
| Contamination | It is acceptable if the dirt can be wiped. | | |

| | SPEC | Acceptable | | |
|-------------------------|--|------------|----------------|--|
| Scratch | W≦0.05 and L≦7 Ignored | | ~~ | |
| | 0.05 <w≦0.08, distance="" l≦7,="">5 n≦3</w≦0.08,> | | | |
| | 0.08 <w≦0.1, distance="" l≦7,="">5 n≦2</w≦0.1,> | | L | |
| | W>0.1 or L>7 | 0 | | |
| Inspection item | SPEC | | Description | |
| | SPEC (unit: mm) | Acceptable | | |
| | D≦0.2 | Ignored | 0 | |
| | Non visible area | Ignored | | |
| Bubble | 0.2 <d≦0.3, distance="">5</d≦0.3,> | n≦3 | D-4 - M0 / 2 | |
| | D>0.3 0 | | D= (L + W) / 2 | |
| | | | | |
| Cover & Sensor Crack | Prohibited | | 4 | |
| | SPEC (unit: mm) | Acceptable | т Т | |
| | Side/Bottom Ignored | | | |
| Cover angle missing | It is prohibited if the defect appears on the front. | 0 | x z + | |
| | | | | |
| Inspection item | SPEC | | Description | |
| Cover edge break | SPEC (unit: mm) | Acceptable | -20 500 14 | |
| | $X \le 2.0, Y \le 2.0, Z \le T$ Ignored | | | |
| | X>2.0, Y>2.0, Z>T | 0 | 7 2 | |
| | | | | |

| Sensor angle | SPEC (unit: mm) Acceptable | | · · |
|-----------------------|--|------------|-----|
| missing/edge break | Damage circuit or function. | | |
| | It can be seen from the front of cover visible area. | 0 | |
| | | | |
| Sensor flange | Sensor flange SPEC (unit: mm) Acceptable | | |
| | Do not affect assembly. Ignored | | |
| | | | |
| Ink | SPEC (unit: mm) Acceptable | | |
| | word unclear, inverted, mistake, break line | 0 | |
| Bubble under | SPEC (unit: mm) | Acceptable | |
| protection film | NA | • | |
| Function | Prohibited | | |

1.3 Sampling Condition

Unless otherwise agree in written, the sampling inspection shall be applied to the incoming inspection of customer.

Lot size: Quantity of shipment lot per model. Sampling type: normal inspection, single sampling

Sampling table: MIL-STD-105E Inspection level: Level II

| | Definition | | |
|------------------|------------|----------|--|
| Class of defects | Major | | It is a defect that is likely to result in failure or to reduce materially the usability of the product for the intended function. |
| | Minor | AQL 1.5% | It is a defect that will not result in functioning problem with deviation classified. |

■ QUALITY ASSURANCE

1.1 Test Condition

1.1.1 Temperature and Humidity(Ambient Temperature)

 $\begin{array}{lll} \text{Temperature} & : & 25 \pm 5^{\circ}\text{C} \\ \text{Humidity} & : & 65 \pm 5\% \\ \end{array}$

1.1.2 Operation

Unless specified otherwise, test will be conducted under function state.

1.1.3 Container

Unless specified otherwise, vibration test will be conducted to the product itself without putting it in a container.

1.1.4 Test Frequency

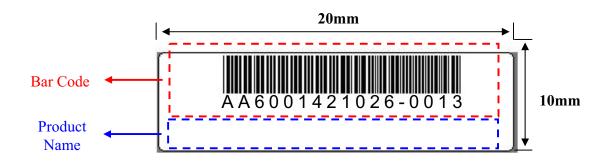
In case of related to deterioration such as shock test. It will be conducted only once.

1.1.5 Test Method

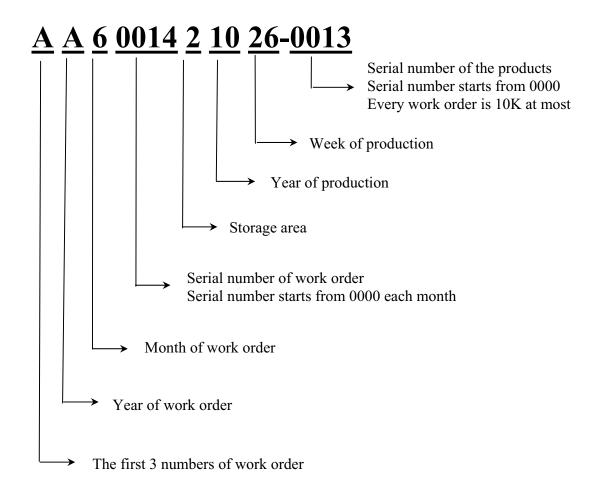
| | Reliability Test Item & Level | Test Level |
|-----|--|---|
| No. | Test Item | |
| 1. | High Temperature Storage Test | T= 70° C, 120hrs after 1 hrs at room temperature and test. |
| 2. | Low Temperature Storage Test | T= -20 $^{\circ}$ C, 120hrs after 1 hrs at room temperature and test. |
| 3. | 3 | T= 40° C, 90%RH,120hrs after 24 hrs at room temperature and test. |
| 4. | Thermal Cycling Test (No operation) | -20 °C 30min ~ 70 °C 30 min , 100 Cycles after 24 hrs at room temperature and test. |
| 5. | Vibration Test (No operation) | Frequency :10 ~ 55 HZ Amplitude :1.5 mm Sweep time : 11 mins Test Period: 6 Cycles for each direction of X, Y, Z |
| 6. | | Air Discharge:±15KV Indirect Contact Discharge:±8KV |

■ CTP PRODUCT LABEL DEFINE

CTP Product Label style:



BarCode Define:



■ PRECAUTIONS IN USE CTP

1. ASSEMBLY PRECAUTIONS

- Since Touch Panel is consist of glass, please be careful your hands to be injured during handing. You must wear gloves during handing.
- (2) Do not touch, push or rub the exposed touch panel, tweezers or anything harder than HB pencil lead. And please do not rub with dust clothes with chemical treatment.
- (3) Do not stack the touch panels together. Do not put heavy objects on touch panel.
- (4) Please do not take a CTP to pieces and reconstruct it. Resolving and reconstructing modules may cause them not to work well.
- (5) Please excessive force or strain to the panel or tail is prohibited, Do not lift touch panel by cable(FPC).
- (6) Use clean sacks or glove to prevent fingerprints and/or stains left on the panel. Extra attention and carefulness should be taken while handling the glass edge.
- (7) Please pay attention for the matters stated below at mounting design of touch panel enclosure. Enclosure support to fix touch panel must be out of active area.(do not design enclosure presses the active area to protect from miss put)

2. OPERATING PRECAUTIONS

- (1) Please be sure to turn off the power supply before connecting and disconnecting signal input cable.
- (2) Please do not change variable resistance settings in CTP. They are adjusted to the most suitable value. If they are changed, it might happen CTP does not satisfy the characteristics specification
- (3) Be careful for condensation at sudden temperature change. Condensation makes damage to sensor or electrical contacted parts.
- (4) CTP has high frequency circuits. Sufficient suppression to the electromagnetic interference shall be done by system manufacturers. Grounding and shielding methods may be important to minimize the interference.
- (5) Touch the panel with your finger or stylus only to assure normal operation. Any sharp edged or hard objects are prohibited.
- (6) Operate the panel in a steady environment. Abrupt variation on temperature and humidity may cause malfunction of the panel.

3. ELECTROSTATIC DISCHARGE CONTROL

(1) The operator should be grounded whenever he/she comes into contact with the CTP. Never touch any of the conductive parts such the copper leads on the FPC and the interface terminals with any parts of the human body.

- (2) The CTP should be kept in antistatic bags or other containers resistant to static for storage.
- (3) Only properly grounded soldering irons should be used.
- (4) If an electric screwdriver is used, it should be well grounded and shielded from commentator sparks.
- (5) The normal static prevention measures should be observed for work clothes and working benches; for the latter conductive (rubber) mat is recommended
- 6) Since dry air is inductive to statics, a relative humidity of 50-60% is recommended.

5. STORAGE PRECAUTIONS

- (1) When you store touch panel for a long time, it is recommended to keep the temperature between 0°C-40°C without the exposure of sunlight and to keep the humidity less than 90%RH.
- (2) Please do not leave touch panel in the environment of high humidity and high temperature such as 60°C 90%RH
- (3) Please do not leave touch panel in the environment of low temperature; below -20°C.

6. OTHERS

For the packaging box, please pay attention to the followings:

- a. Please do not pile them up more than 5 boxes. (They are not designed so.) And please do not turn over.
- Please handle packaging box with care not to give them sudden shock and vibrations. And also please do not throw them up.
- c. Packing box and inner case for CTP are made of cardboard. So please pay attention not to get them wet. (Such like keeping them in high humidity or wet place can occur getting them wet.)

7. LIMITED WARRANTY

Unless otherwise agreed between Display Future and customer, Display Future will replace or repair any of its CTP which is found to be defective electrically and visually when inspected in accordance with Display Future acceptance standards, for a period on one year from date of shipment. Confirmation of such date shall be based on freight documents. The warranty liability of Display Future is limited to repair and/or replacement on the terms set forth above. Display Future will not responsible for any subsequent or consequential events.

■ OUTLINE DRAWING

