

# MULTI-INNO TECHNOLOGY CO., LTD.

## www.multi-inno.com

## **LCD MODULE SPECIFICATION**

## Model : MI0570ET-8

This module uses ROHS material

## For Customer's Acceptance:

Customer		
Approved		
Comment		

This specification may change without prior notice in	Revision	1.0
order to improve performance or quality. Please contact	Engineering	
Multi-Inno for updated specification and product status	Date	2013-11-20
before design for this product or release of this order.	Our Reference	



## **REVISION RECORD**

REV NO.	REV DATE	CONTENTS	REMARKS
1.0	2013-11-20	Preliminary Specification Release	



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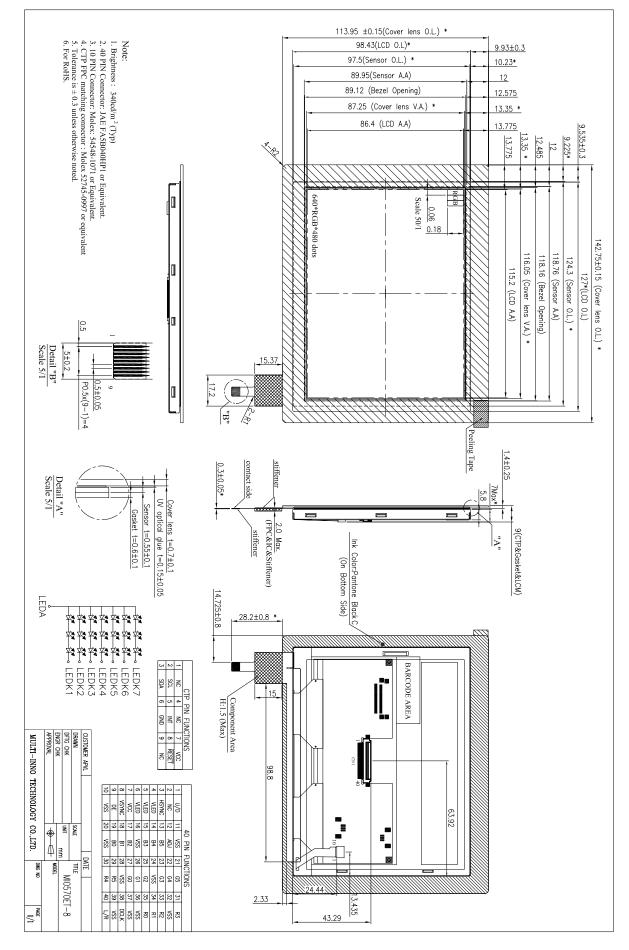
## ■ GENERAL INFORMATION

Item	Contents	Unit
LCD type	TFT	/
Size	5.7	Inch
Viewingdirection	6:00(without image inversion and least brightness change)	O' Clock
Gray scale inversion direction	12:00(contrast peak located at)	O'Clock
$LCM(W \times H \times D)$	142.75×113.95×9.00	mm <sup>3</sup>
Active area (W×H)	115.20×86.40	mm <sup>2</sup>
Dot pitch (W×H)	0.06×0.18	mm <sup>2</sup>
Number of dots	640 (RGB) × 480	/
Backlight type	21 LEDs	/
Driver IC	Gate:HX8628A Source:HX8250-A	/
CTP IC	GT927	/
Interface type	RGB 18 bits	/
Color depth	262K	/
Color configuration	R.G.B stripe	/
Surface treatment	Clear	/
Input voltage	3.3	V
With/Without TSP	With CTP	/
Weight	TBD	g

Note 1: RoHS compliant; Note 2: LCM weight tolerance:  $\pm 5\%$ .

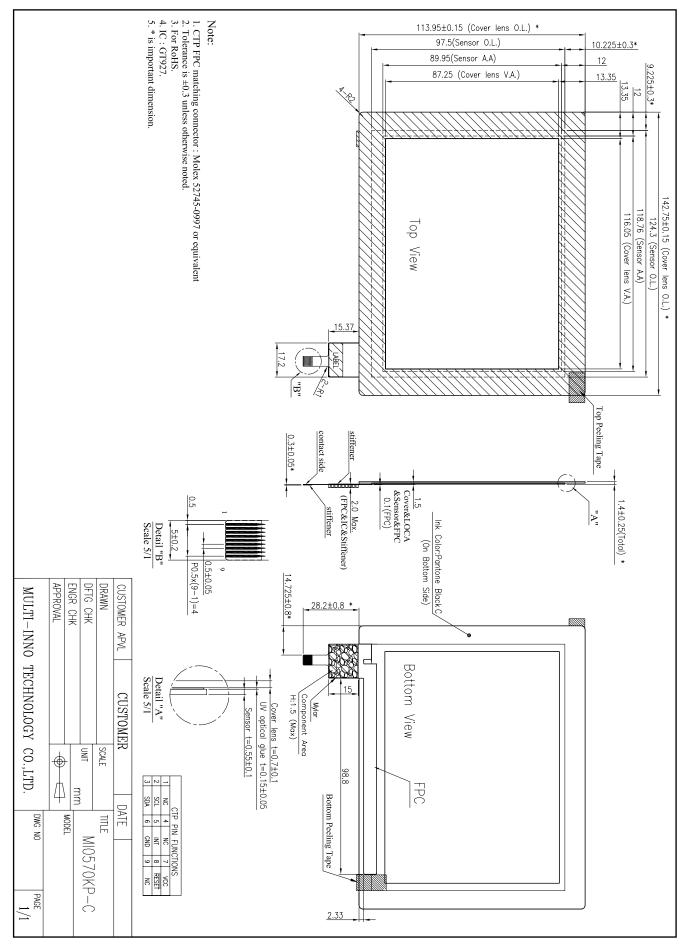


## EXTERNAL DIMENSIONS





## **CTP OUTLINE DRAWING**





## ■ABSOLUTE MAXIMUM RATINGS

Parameter	Symbol	Min	Max	Unit
Power supply voltage	VCC	-0.3	5.0	V
Logic input voltage	VI	-0.3	VCC+0.3	V
Operating temperature	Тор	-20	70	°C
Storage temperature	Тѕт	-30	80	°C
Humidity	RH	-	90%(Max60°C)	RH

## **ELECTRICAL CHARACTERISTICS**

Parameter	Symbol	Min	Тур	Max	Unit
Power supply voltage for LCD	VCC	3.0	3.3	3.6	V
Power supply current for LCD	ICC	-	111	140	mA
Power supply voltage for LED	VLED	4.5	5	5.5	V
Power supply current for LCD	I led	-	333	400	mA
Ripple voltage	$V_{RF}$	-	-	100	mVp-p
Input voltage ' H ' level	Vih	0.7VCC	-	VCC	V
Input voltage ' L ' level	VIL	0	-	0.3VCC	V
ADJ frequency	-	19K	20K	21K	Hz
ADJ input voltage	Vih	3.0	-	3.3	V
ADJ input voltage	Vil	0	-	0.3	V
LED life time	-	-	50,000	-	Hr

Note 1: The "LED life time" is defined as the module brightness decrease to 50% original brightness that the ambient temperature is  $25^{\circ}$ C and ADJ = 3.3V.





## **ELECTRO-OPTICAL CHARACTERISTICS**

Item		Symbol	Condition	Min	Тур	Max	Unit	Remark	Note
Response	Response time			-	50	-	ms	FIG 1.	4
Contrast r	ratio	Cr	θ=0°	200	300	-		FIG 2.	1
Luminance uniformity		δ WHITE	Ø=0° Ta=25℃	70	80	-	%	FIG 2.	3
Surface Lum	inance	Lv		300	340	-	cd/m <sup>2</sup>	FIG 2.	2
			$\emptyset = 90^{\circ}$	50	60	-	deg	FIG 3.	
Viewing angl	0 100 00	0	$\emptyset = 270^{\circ}$	30	40	-	deg	FIG 3.	
Viewing angle range		θ	$\emptyset = 0^{\circ}$	60	70	-	deg	FIG 3.	6
			$\varnothing = 180^\circ$ 60 70 - de		deg	FIG 3.			
	Red	X		0.565	0.615	0.665			
	Reu	у		0.310	0.360	0.410			
	Green	X	θ=0°	0.295	0.345	0.395			
CIE (x, y)	Ulteri	у	Ø=0°	0.490	0.540	0.590		FIG 2.	5
chromaticity	Blue	Х		0.098	0.148	0.198		110 2.	5
	Diuc	у	1 a-25 C	0.056	0.106	0.156			
	White	X		0.259	0.309	0.359			
	white	у		0.270	0.320	0.370			
Image sticking	-	tis	2 hours	-	-	2	Sec	-	8

Note 1. Contrast Ratio(CR) is defined mathematically as For more information see FIG 2.:

Contrast Ratio =  $\frac{\text{Average Surface Luminance with all white pixels } (P_1, P_2, P_3, P_4, P_5)}{\text{Average Surface Luminance with all black pixels } (P_1, P_2, P_3, P_4, P_5)}$ 

Note 2. Surface luminance is the LCD surface from the surface with all pixels displaying white. For more information see FIG 2.

Lv = Average Surface Luminance with all white pixels  $(P_1, P_2, P_3, P_4, P_5)$ 

Note 3. The uniformity in surface luminance ,  $\delta$  WHITE is determined by measuring luminance at each test position 1 through 5, and then dividing the maximum luminance of 5 points luminance by minimum luminance of 5 points luminance. For more information see FIG 2.

 $\delta \text{ WHITE} = \frac{\text{Minimum Surface Luminance with all white pixels } (P_1, P_2, P_3, P_4, P_5)}{\text{Maximum Surface Luminance with all white pixels } (P_1, P_2, P_3, P_4, P_5)}$ 

- Note 4. Response time is the time required for the display to transition from White to black(Rise Time, Tr) and from black to white(Decay Time, Tf). For additional information see FIG 1. The test equipment is Autronic-Melchers's ConoScope. Series
- Note 5. CIE (x, y) chromaticity, The x, y value is determined by measuring luminance at each test position 1 through 5, and then make average value
- Note 6. Viewing angle is the angle at which the contrast ratio is greater than 2. For TFT module the conrast ratio is greater than 10. The angles are determined for the horizontal or x axis and the vertical or y axis with respect to the z axis which is normal to the LCD surface. For more information see FIG 3.
- Note7. For Viewing angle and response time testing, the testing data is base on Autronic-Melchers's ConoScope. Series Instruments. For contrast ratio, Surface Luminance, Luminance uniformity,CIE The test data is base on TOPCON's BM-5 photo detector.



#### FIG. 1 The definition of Response Time

The response time is defined as the following figure and shall be measured by switching the input signal for "black" and "white".

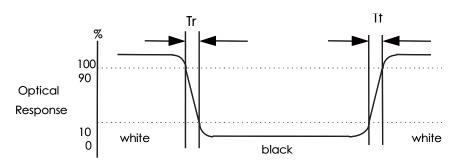
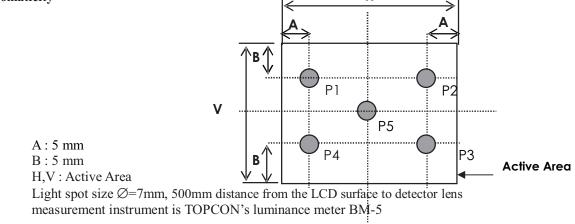
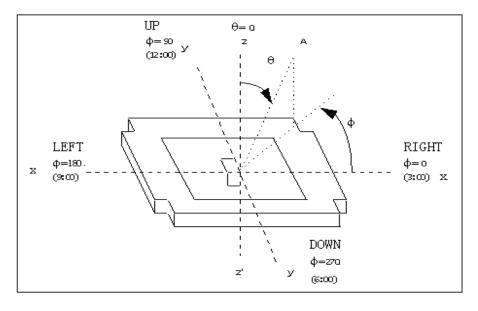


FIG. 2 Measuring method for Contrast ratio, surface luminance, Luminance uniformity, CIE (x, y) chromaticity



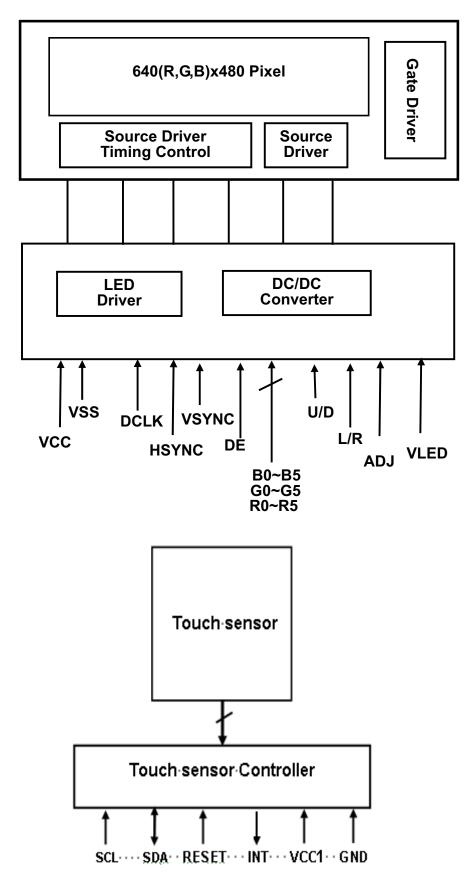
#### FIG. 3 The definition of viewing angle





## ■ INTERFACE DESCRIPTION

## 1. BLOCK DIAGRAM





## **2. PIN CONNECTIONS**

Pin NO.	SYMBOL	DESCRIPTION
1	U/D	Up or Down Display Control
2	NC	No Connection
3	Hsync	Horizontal SYNC.
4	VLED	Power Supply for LED Driver circuit
5	VLED	Power Supply for LED Driver circuit
6	VLED	Power Supply for LED Driver circuit
7	Vcc	Power Supply for LCD
8	Vsync	Vertical SYNC.
9	DE	Data Enable
10	VSS	Power Ground
11	VSS	Power Ground
12	ADJ	Brightness control for LED B/L
13	B5	Blue Data 5 (MSB)
14	B4	Blue Data 4
15	B3	Blue Data 3
16	Vss	Power Ground
17	B2	Blue Data 2
18	B1	Blue Data 1
19	B0	Blue Data 0 (LSB)
20	Vss	Power Ground
21	G5	Green Data 5 (MSB)
22	G4	Green Data 4
23	G3	Green Data 3
24	Vss	Power Ground
25	G2	Green Data 2
26	G1	Green Data 1
27	G0	Green Data 0 (LSB)
28	Vss	Power Ground
29	R5	Red Data 5 (MSB)
30	R4	Red Data 4
31	R3	Red Data 3
32	Vss	Power Ground
33	R2	Red Data 2
34	R1	Red Data 1
35	R0	Red Data 0
36	VSS	Power Ground
37	VSS	Power Ground
38	DCLK	Clock Signals ; Latch Data at the Falling Edge
39	Vss	Power Ground
40	L/R	Left or Right Display Control

Remarks :

ADJ is brightness control Pin. The larger of the pulse duty is, the higher of the brightness.
ADJ signal is 0~3.3V.Operation frequency is 20KHz
VSS PIN must be grounding, can not be floating.

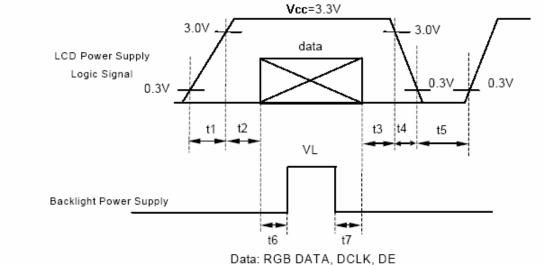
4) U/D and L/R control Function	
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L/R	U/D	Function
1	0	Normally display
0	0	Left and Right opposite
1	1	Up and Down opposite
0	1	Left and Right opposite <sup>,</sup> Up and Down opposite

5)If DE signal is fixed low, SYNC mode is used. Otherwise, DE mode is used.

#### 8.1 Power Signal Sequence

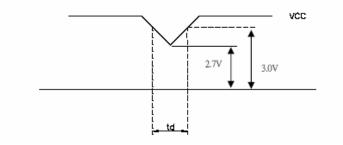
Remarks: \*1) Power Signal sequence:  $t1 \le 10ms$  : 1 sec $\le t5$  $50ms \le t2$  : 200ms  $\le t6$  $0 < t3 \le 50ms$ : 200ms $\le t7$  $0 < t4 \le 10ms$ 



\*2) VCC-dip condition:

(1) 2.7 V  $\leq$  VCC <3.0V,td  $\leq$  10 ms

(2) VCC  $\!>\!3.0V,\!VCC$  -dip condition should be the same with VCC-turn-on condition  $\circ$ 





## ■ APPLICATION NOTES

## **1. INTERFACE SPECIFICATIONS**

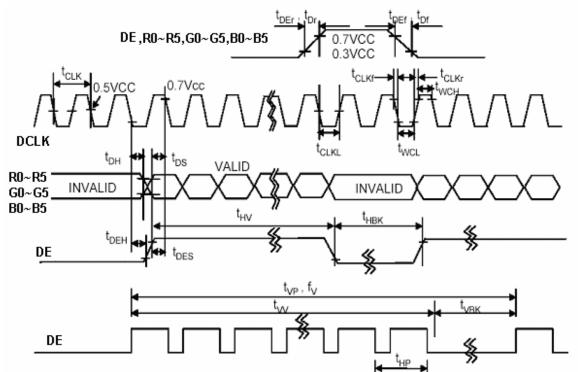
#### **1.1 DE mode Input signal characteristics**

Signal	Parameter	Symbol	MIN.	TYP.	MAX.	Unit	Remarks
DCLK	Period	tськ	33	40	43	ns	
	Frequency	fclk	23	25	30	MHz	
	Low Level Width	t <sub>wcL</sub>	6	-	-	ns	
	High Level Width	t <sub>wcн</sub>	6	-	-	ns	
	Rise, Fall Time	t_t	-	-	3	ns	
	Duty	-	0.45	0.50	0.55	-	
DE	Setup Time	t <sub>DES</sub>	5	-	-	ns	
(Data	Hold Time	t <sub>DEH</sub>	10	-	-	ns	
Enable)	Rise, Fall Time	t_t DEr, DEf	-	-	16	ns	
	Horizontal Period	t <sub>HP</sub>	750	800	900	t <sub>CLK</sub>	
	Horizontal Valid	t <sub>HV</sub>	640	640	640	t <sub>CLK</sub>	
	Horizontal Blank	t <sub>нвк</sub>	110	160	260	t <sub>ськ</sub>	
	Vertical Period	t <sub>vP</sub>	515	525	560	t <sub>HP</sub>	
	Vertical Valid	t <sub>w</sub>	480	480	480	t <sub>HP</sub>	
	Vertical Blank	t <sub>vBK</sub>	35	45	80	t <sub>HP</sub>	
	Vertical Frequency	f	55	60	65	Hz	
Data	Setup Time	t <sub>DS</sub>	5	-	-	ns	
R,G,B	Hold Time	t <sub>DH</sub>	10	-	-	ns	
	Rise, Fall Time	t_t <sub>Dr, Df</sub>	-	-	3	ns	

Note: (1) tCLKL / tCLK.



#### 1.1 DE mode timing waveform

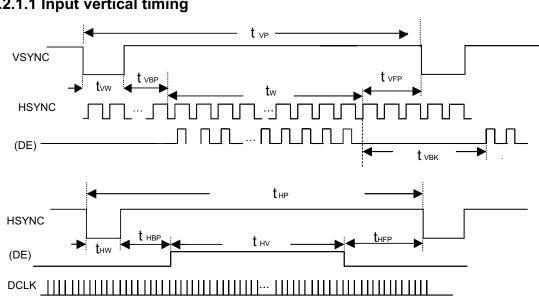


## **1.2 SYNC mode Input signal characteristics**

Parameter	Symbol	MIN.	TYP.	MAX.	Unit	Remarks
Clock Period	t <sub>CLK</sub>	33	40	43	ns	
Clock Frequency	f <sub>ськ</sub>	23	25	30	MHz	
Clock Low Level Width	t <sub>wcL</sub>	6	-	-	ns	
Clock High Level Width	t <sub>wcн</sub>	6	-	-	ns	
Clock Rise, Fall Time	t_t	-	-	3	ns	
HSYNC Period	t <sub>HP</sub>	750	800	900	t <sub>CLK</sub>	
HSYNC Pulse Width	t <sub>HW</sub>	5	30	-	t <sub>CLK</sub>	
HSYNC Front Porch	t <sub>HFP</sub>	1	16	116	t <sub>CLK</sub>	
HSYNC Back Porch	t <sub>HBP</sub>	1	114	139	t <sub>CLK</sub>	
HSYNC Width + Back Porch	t <sub>HW</sub> +t <sub>HBP</sub>	144	144	144	t <sub>CLK</sub>	
Horizontal Blank	t <sub>нвк</sub>	1	160	260	t <sub>cLK</sub>	
Horizontal Valid	t <sub>HV</sub>	640	640	640	t <sub>CLK</sub>	
VSYNC Period	t <sub>vP</sub>	515	525	560	t <sub>HP</sub>	
VSYNC Pulse Width	t <sub>vw</sub>	1	3	5	t <sub>HP</sub>	
VSYNC Front Porch	t <sub>vFP</sub>	1	10	45	t <sub>HP</sub>	
VSYNC Back Porch	t <sub>vBP</sub>	30	32	34	t <sub>HP</sub>	
VSYNC Width + Back Porch	t <sub>vw</sub> +t <sub>vbp</sub>	35	35	35	t <sub>CLK</sub>	
Vertical Blank	t <sub>vBK</sub>	35	45	80	t <sub>HP</sub>	
Vaild data Width	t <sub>w</sub>	480	480	480	t <sub>HP</sub>	
Data Setup Time	t <sub>DS</sub>	5	-	-	ns	
Data Hold Time	t <sub>DH</sub>	10	-	-	ns	
Note: (1) tHBK = tHFP + tHW + tHBP						

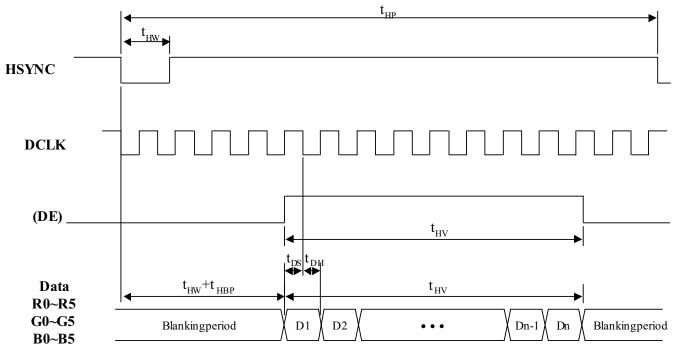
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#### 1.2.1 SYNC mode timing waveform 1.2.1.1 Input vertical timing

Remark : If SYNC mode is used, please fix DE signal to low, DE timing waveform is for reference only. **1.2.1.2 Input horizontal timing** 



Remark : If SYNC mode is used, please fix DE signal to low, DE timing waveform is for reference only.



#### **1.3 Color Data Assignment**

0 00101	Data ASSI	ginnei																	
COLOR	INPUT		F	R DA	TA					<u>G D</u>	ATA			B DATA					
	DATA	R5	R4	R3	R2	R1	R0	G5	G4	G3	G2	G1	G0	B5	В4	В3	B2	B1	В0
		MSB					LSB	MSB					LSB	MSB					LSB
	BLACK	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	RED(63)	1	1	1	1	1	1	0	0	0	0	0	0	0	0	0	0	0	0
	GREEN(63)	0	0	0	0	0	0	1	1	1	1	1	1	0	0	0	0	0	0
BASIC COLOR	BLUE(63)	0	0	0	0	0	0	0	0	0	0	0	0	1	1	1	1	1	1
OOLOIN	CYAN	0	0	0	0	0	0	1	1	1	1	1	1	1	1	1	1	1	1
	MAGENTA	1	1	1	1	1	1	0	0	0	0	0	0	1	1	1	1	1	1
	YELLOW	1	1	1	1	1	1	1	1	1	1	1	1	0	0	0	0	0	0
	WHITE	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
	RED(0)	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	RED(1)	0	0	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0
	RED(2)	0	0	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0
RED	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:
	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:
	RED(62)	1	1	1	1	1	0	0	0	0	0	0	0	0	0	0	0	0	0
	RED(63)	1	1	1	1	1	1	0	0	0	0	0	0	0	0	0	0	0	0
	GREEN(0)	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	GREEN(1)	0	0	0	0	0	0	0	0	0	0	0	1	0	0	0	0	0	0
	GREEN(2)	0	0	0	0	0	0	0	0	0	0	1	0	0	0	0	0	0	0
GREEN	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:
	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:
	GREEN(62)	0	0	0	0	0	0	1	1	1	1	1	0	0	0	0	0	0	0
	GREEN(63)	0	0	0	0	0	0	1	1	1	1	1	1	0	0	0	0	0	0
	BLUE(0)	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
	BLUE(1)	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1
	BLUE(2)	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0
BLUE	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:
	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:	:
	BLUE(62)	0	0	0	0	0	0	0	0	0	0	0	0	1	1	1	1	1	0
	BLUE(63)	0	0	0	0	0	0	0	0	0	0	0	0	1	1	1	1	1	1

Remarks:(1) Definition of Gray Scale

color(n):n is series of Gray Scale The more n value is, the bright Gray Scale.

(2)Data:1-High,0-Low

Correspondence between Data and Display Position

	S0001	S0002	S0003	S0004	S0005	S0006	S0007	S0008		-S1919	S1920
C001	R001	G001	B001	R002	G002	B002	R003	G003		G640	B640
i											
									1		.
1										ļ	
C480	R001	G001	B001	R002	G002	B002	R003	G003		G640	B640



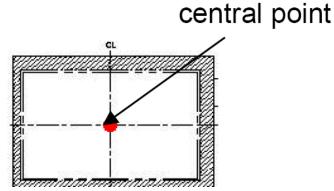
## ■ CTP GENERAL SPECIFICATIONS

#### 1.1 CTP main feature

Item	Specification	Unit
Туре	Transparent type projected capacitive touch panel	
Input mode	Human's finger	
Finger	10	
Sensor Active Area	118.76(W)(typ.) x89.95(H)(typ.)	mm
Transparency	≧85%	%
Haze	≦2.0%	%
Origin Point	The upper left corner	
Hardness	7H (typ.) [by JIS K5400]	Pencil hardness
Report rate	Max: 122	Points/sec
Response time	15	ms
Point hitting life time	1,000,000 times min.	Note 1

Note 1: Use 8 mm diameter silicon rubber/force 3N to knock on the same point twice per

second (no-operating), after test function check pass.



### 1.2 CTP Absolute Maximum Rating

Symbol	Description	Min	Тур.	Мах	Unit	Notes
VCC1	Supply voltage	2.66	-	3.47	V	
VIO	DC input voltage	0	-	VCC1+0.3	V	

#### **1.3 CTP Electrical Characteristics**

Symbol	Description	Min	Тур	Max	Unit	Notes
VCC1	Supply voltage	2.8	-	3.3	V	
GND	Supply voltage	-	0	-	V	
	Active mode	-	13	15	mA	
VIH	Input H voltage	1.35	1.8	2.1	V	
VIL	Input L voltage	-0.3	0	0.45	V	



#### **1.4 CTP Pin Connections**

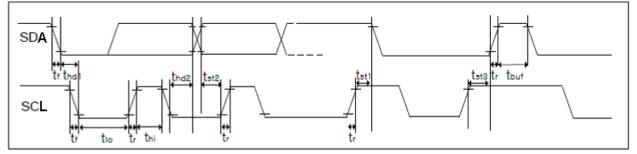
No.	Name	I/O	Description
1	NC	-	No connection
2	SCL	I	l <sup>2</sup> C Clock
3	SDA	I/O	I <sup>2</sup> C Data
4	NC	-	No connection
5	INT	0	Interrupt output
6	GND	Р	Ground
7	VCC1	Р	Power supply Voltage
8	/RESET	I	Reset active low
9	NC	-	No connection

### 1.5 CTP Interface and Data Format [Slave address is 0x5D( 7 bit addressing )]

Communication protocol: I<sup>2</sup>C

Clock frequency : 100Khz (400Khz Fast mode)

Below is timing of I2C hardware circuit:



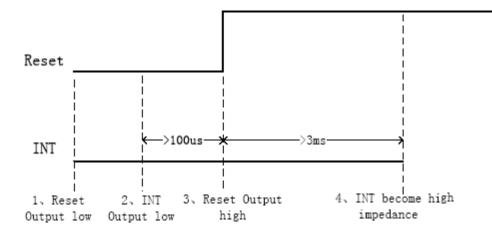
Test condition 1: 3.3V communication interface, 400Kbps, pull up resistor is 2K ohm

Parameter	Symbol	Min	Max	Unit
SCL low period	t <sub>lo</sub>	0.9	0.9	us
SCL high period	t <sub>hi</sub>	0.8	0.8	us
SCL setup time for START condition	t <sub>st1</sub>	0.4	0.4	us
SCL setup time for STOP condition	t <sub>st3</sub>	0.4	0.4	us
SCL hold time for START condition	t <sub>st1</sub>	0.3	0.3	us
SDA setup time	t <sub>st2</sub>	0.4	0.4	us
SDA hold time	t <sub>st2</sub>	0.4	0.4	us

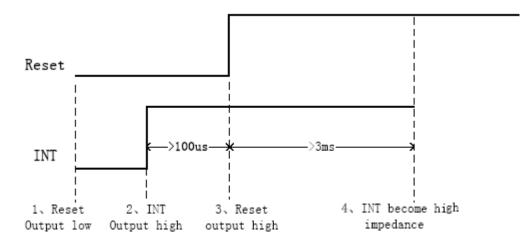
GT927 has 2 sets of slave address 0xBA/0xBB or 0x28/0x29. Master can control Reset & INT pin to configure the slave address the slave address in power on initial state like following:



#### 1.5.1 Timing of setting slave address to 0xBA/0XBB:



#### 1.5.2 Timing of setting slave address to 0x28/0X29:



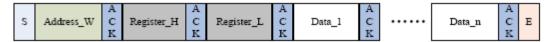
#### a) Data Transmission (ex: slave address is 0xBA/0xBB)

Communication is always initiated by master, A high-to-low transition of SDA with SCL high is a start condition.

All addresses words are serially transmitted to and from on bus in 8-bit words. GT927 sends a "0" to acknowledge when the address word is 0xBA/BB. This happens during the ninth clock cycle. If the slave address is not matched, GT927 will stay in idle state.

The data words are serially transmitted to and from in 9-bit words: 8-bit data + 1-bit ACK or NACK sent by GT927. Data changes during SCL high periods.

A low-to-high transition of SDA with SCL high is a stop condition.b) Write Operations to GT927 (ex: slave address is 0xBA/0xBB)



#### Write Operations

Please check above figure, master start the communication first, and then sends address words 0XBA for a write operation.

After receiving ACK from GT927, master sends out register address word in 16-bit, and then the data word in 8-bit, which is going to be wrote into GT927.

GT927's address pointer will be automatically added 1 after write operation, so master can sequential write in one operation. When operation finished, master stop the communication.

#### c) Read Operations to GT927 (ex: slave address is 0xBA/0xBB)

s	Address_W	A C K	Register_H	A C K	Register_L	A C K	E	s	Address_R	A C K	Data_l	A C K		Data_n	N A C K
		Se	t start register a	addre	55 🗲						► Re	ead dat	ta 🗕		

#### Read operation

Please check above figure, master start the communication first, and then sends address words 0xBA for a write operation.

After receiving ACK from GT927, master sends out register address word in 16-bit, to set GT927's address pointer. After receiving ACK, master sends out a start signal once again, start the read operation with command: 0xBB, and read data word from GT927 in 8-bit.

GT927 also supports sequential read operation, and the default setting is sequential read mode. Master shall send out ACK when receiving successfully in every data word, master sends NACK after getting all the data required, then sends stop signal to finish the communication.



### **1.5.3 Register Information of GT927 a) Real Time Order** (Write Only)

Addr	Name	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0x8040	Command							software tion 5: sc	
0x8041	LED_Control	Control word under control of touch key LED light						ght	
0x8042	Proximity_En	Proximity switch							

#### **b)** Configuration Information (R/W)

0x8047     Config_Version     Version number of configuration document       0x8048     X Output Max L     Max value of X axis       0x804A     Y Output Max L     Max value of Y axis       0x804A     Y Output Max L     Max value of Y axis       0x804B     Y Output Max H     Max value of Y axis       0x804D     Module_Switch1     Reserved     Touch number: 1~5       0x804F     Shake Count     Reserved     Touch number of coordinate window, coefficiency is 1)       0x8050     Filter     First_Filter     Norma_Filter(filtering value of of outh in large area       0x8051     Large_Touch     Number of touch in large area     Value of noise elimination(coefficient is 1)       0x8052     Noise_Reduction     Reserved     Threshold of touch grow out of nothing       0x8055     Low_Power_Control     Reserved     Time to low power consumption(0~15s)       0x8056     Refersh_Rate     Reserved     Coordinate report rate(Cycle: 5+N ms)       0x8056     X_threshold     Reserved     Silank area of boarder-top       0x8057     X_threshold     Reserved     Solarder-top       0x8058     Y_threshold	Addr	Name	Bit7	Bite		Bit5	Bit4	Bit3	Bit2	Bit1	Bit0
0x8048     X Output Max L     Max value of X axis       0x8049     X Output Max L     Max value of Y axis       0x804A     Y Output Max L     Max value of Y axis       0x804A     Y Output Max H     Max value of Y axis       0x804A     Y Output Max H     Reserved     Toucn number: 1-5       0x804D     Module_Switch1     Reserved     Streth_rank     X2Y     Sito     INT trigger method       0x804E     Module_Switch2     Reserved     Finger shake count     Key     Streth_rank     X2Y     Sito     INT trigger method       0x8051     Large_Touch     Reserved     Finger shake count     Streth_rank     Normal_Filter(filtering value of original coordinate window, coefficiency is 1)       0x8052     Noise_Reduction     Reserved     Value of notise elimination(coefficient is 1)     Streth_rank preserved     Streth_rank			ыц								DILU
Ox8049     X Output Max H     Max Value of X axis       0x804A     Y Output Max L     Max value of Y axis       0x804B     Y Output Max H     Max value of Y axis       0x804C     Touch Number     Reserved     Touch number: 1-5       0x804B     Module_Switch1     Reserved     Stretch_rank     X2Y     Sito     INT trigger method       0x804E     Module_Switch2     Reserved     Touch rumber: 1-5     Touch Key     Touch Key       0x8050     Filter     Shake_Count     Reserved     Touch in large area     Touch Key       0x8051     Large_Touch     Number of touch in large area     Value of noise elimination(coefficient is 1)       0x8052     Noise_Reduction     Reserved     Threshold of touch grow out of nothing       0x8053     S_fouch_Level     Threshold of touch grow out of nothing     Sito       0x8055     Low_Power_Control     Reserved     Coordinate report rate(Cycle: 5+N ms)       0x8056     Refresh_Rate     Reserved     Coordinate rea of boarder-bottom       0x8057     x_threshold     Reserved     Sito     Soarder-right       0x8056				V	ersi	on numi		onngui	ation uo	cument	
0x804A     Y Output Max_L     Max value of Y axis       0x8042     Y Output Max_H     Touch Number     Touch Number     Touch Number: 1~5       0x804D     Module_Switch1     Reserved     Stretch_rank     X2Y     Sito     INT trigger method       0x804E     Module_Switch2     Reserved     Touch Key     Touch Key       0x804F     Shake_Count     Reserved     Filter/filtering value of original coordinate window, coefficiency is 1)       0x8051     Large_Touch     Number of touch in large area     Oxedficiency is 1)       0x8052     Noise_Reduction     Reserved     Value of nothing       0x8053     S_Touch Level     Threshold of touch grow out of nothing       0x8055     Low_Power_Control     Reserved     Coordinate report rate(Cycle: 5+N ms)       0x8056     Refresh_Rate     Reserved     Coordinate report rate(Cycle: 5+N ms)       0x8057     x_threshold     Value of boarder-top     Blank area of boarder-top       0x8058     y_threshold     Reserved     Coordinate report rate(Cycle: 5+N ms)       0x8056     NC     Reserved     Served       0x8055     NC		·				Μ	ax val	ue of X	axis		
Ox804B     Y Output Max_H     Max Value of Y axis       0x804C     Touch Number     Reserved     Touch number: 1~5       0x804D     Module_Switch1     Reserved     Stretch_rank     X2Y     Sito     INT trigger method       0x804E     Module_Switch2     Reserved     Finger shake count     Finger shake count       0x8050     Filter     Shake_Count     Reserved     Finger shake count     Key       0x8051     Large_Touch     Number of touch in large area     Number of touch in large area     Nose_Reduction     is 1)       0x8053     S_Touch_Level     Threshold of touch grow out of nothing     Time to low power consumption(0~15s)       0x8054     S_Leave_Level     Threshold of touch grow out of nothing     Coordinate report rate(Cycle: 5+N ms)       0x8055     Low_Power_Control     Reserved     Coordinate report rate(Cycle: 5+N ms)       0x8056     Refresh_Rate     Reserved     Coordinate report rate(Cycle: 5+N ms)       0x8056     Space     Blank area of boarder-top     Blank area of boarder-top     Blank area of boarder-top       0x8057     X threshold     Reserved     Seerved     Ox8056											
0x804C     Touch Number     Reserved     Touch number: 1~5       0x804D     Module_Switch1     Reserved     Stretch_rank     X2Y     Sito     INT trigger method       0x804E     Module_Switch2     Reserved     Stretch_rank     X2Y     Sito     INT trigger method       0x8050     Filter     Shake_Count     Reserved     Filter(filtering value of original coordinate window, coefficiency is 1)       0x8051     Large_Touch     Number of touch in large area     Value of noise elimination(coefficient is 1)       0x8052     Noise_Reduction     Reserved     Time to low power out of nothing       0x8053     S_Touch_Level     Threshold of touch grow out of nothing     Time to low power consumption(0~15s)       0x8055     Low_Power_Control     Reserved     Coordinate report rate(Cycle: 5+N ms)       0x8056     x_threshold     Reserved     Seerved     Seerved       0x8056     Space     Blank area of boarder-top     Blank area of boarder-topt     Blank area of boarder-right       0x8057     NC     Reserved     Driver Group_A number     Reserved     Seerved       0x8056     NC     Reserved <td></td> <td></td> <td></td> <td></td> <td></td> <td>Μ</td> <td>ax val</td> <td>ue of Y</td> <td>axis</td> <td></td> <td></td>						Μ	ax val	ue of Y	axis		
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0x804F     Shake_Count     Reserved     Finger shake count       0x8050     Filter     First_Filter     Normal_Filter/filtering value of original coordinate window, coefficiency is 1)       0x8051     Large_Touch     Number of touch in large area     Value of noise elimination(coefficient is 1)       0x8052     Noise_Reduction     Reserved     Value of noise elimination(coefficient is 1)       0x8053     S_Touch_Level     Threshold of touch grow out of nothing     is 1)       0x8054     S_Leave_Level     Threshold of touch grow out of nothing     0x8055       0x8055     Low_Power_Control     Reserved     Coordinate report rate(Cycle: 5+N ms)       0x8056     Refresh_Rate     Reserved     Coordinate report rate(Cycle: 5+N ms)       0x8058     y_threshold     Reserved     Coordinate area of boarder-top       0x8058     Space     Blank area of boarder-top     Blank area of boarder-top       0x8058     Space     Blank area of boarder-top     Blank area of boarder-right       0x8050     NC     Reserved     Reserved       0x8055     NC     Reserved     Driver_Group_A_num       0x8060     NC			Reser	ved			nk	X2Y		m	ethod
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0x8054     S_Leave_Level     Threshold of touch grow out of nothing       0x8055     Low_Power_Control     Reserved     Time to low power consumption(0~15s)       0x8056     Refresh_Rate     Reserved     Coordinate report rate(Cycle: 5+N ms)       0x8057     x_threshold     Reserved     5+N ms)       0x8058     y_threshold     Reserved     Stevent       0x8059     X_Speed_Limit     Parameter of speed limit     0x8058       0x8050     Space     Blank area of boarder-top     Blank area of boarder-top       0x8050     NC     Reserved     Reserved       0x8051     NC     Reserved     Norder-top       0x8052     NC     Reserved     Reserved       0x8055     NC     Reserved     Reserved       0x8056     NC     Reserved     Reserved       0x8055     NC     Reserved     Reserved       0x8060     NC     Reserved     Driver_Group_A_number       0x8061     NC     Reserved     Driver_Group_B_number       0x8062     Drv_GroupB_Num     Reserved     Driver_Group_				Rese						/	
0x8055     Low_Power_Control     Reserved     Time to low power consumption(0~15s)       0x8056     Refresh_Rate     Reserved     Coordinate report rate(Cycle: 5+N ms)       0x8057     x_threshold     Reserved     Speed_Limit       0x8058     y_threshold     Reserved     Speed_Limit       0x8058     y_threshold     Parameter of speed limit       0x8058     Y_Speed_Limit     Parameter of speed limit       0x8058     Space     Blank area of boarder-top     Blank area of boarder-bottom       0x8050     NC     Reserved     Reserved       0x8055     NC     Reserved     Reserved       0x8056     NC     Reserved     Reserved       0x8055     NC     Reserved     Reserved       0x8061     NC     Reserved     Driver_Group_A_number       0x8063     Drv_GroupA_Num     All Driving Reserved     Driver_Group_A_number       0x8064     Sensor_Num     Sensor_Group_B_Number     Sensor_Group_A_Num Area of Driver group A       0x8066     FreqA_factor     Driver frequency double frequency coefficient of Driver group A       0x8066 <td></td>											
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Ox805CSpaceBlank area of boarder-leftBlank area of boarder-right0x805DNCReserved0x805ENCReserved0x805FNCReserved0x8060NCReserved0x8061NCReserved0x8062Drv_GroupA_NumAll_Driving0x8063Drv_GroupB_NumReserved0x8064Sensor_Num0x8065FreqA_factor0x8066FreqA_factor0x8066FreqB_factor0x8067Pannel_BitFreqL0x8068Pannel_BitFreqH0x8069Pannel_Sensor_TimeLTime interval of the paibouring two driving signal/(Init: us)		Y_Speed_Limit									
0x805CNCReservedBlank area of boarder-leftBlank area of boarder-left0x805DNCReserved0x805ENCReserved0x805FNCReserved0x8060NCReserved0x8061NCReserved0x8062Drv_GroupA_NumAll_Driving0x8063Drv_GroupB_NumReserved0x8064Sensor_Num0x8065FreqA_factor0x8066FreqB_factor0x8067Pannel_BitFreqL0x8068Pannel_BitFreqH0x8069Pannel_Sensor_TimeL		Space									
0x805E   NC   Reserved     0x805F   NC   Reserved     0x8060   NC   Reserved     0x8061   NC   Reserved     0x8062   Drv_GroupA_Num   All_Driving   Reserved     0x8063   Drv_GroupB_Num   Reserved   D_Freq     0x8064   Sensor_Num   Sensor_Group_B_Number   Sensor_Group_A_Number     0x8065   FreqA_factor   Driver frequency double frequency coefficient of Driver group A GroupA_Frequence =Multiplier factor *baseband     0x8066   FreqB_factor   Driver frequency double frequency coefficient of Driver group B GroupB_Frequence =Multiplier factor *baseband     0x8067   Pannel_BitFreqL   Baseband of Driver group A\B(1526Hz <baseband<14600hz)< td="">     0x8068   Pannel_BitFreqH   Time interval of the neibouring two driving signal/(Linit; us)</baseband<14600hz)<>		•	Blan	k area	of	boarder-	left	Blar	nk area o	of board	er-right
0x805F     NC     Reserved       0x8060     NC     Reserved       0x8061     NC     Reserved       0x8062     Drv_GroupA_Num     All_Driving     Reserved     Driver_Group_A_number       0x8063     Drv_GroupB_Num     Reserved     D_Freq     Driver_Group_B_number       0x8064     Sensor_Num     Sensor_Group_B_Number     Sensor_Group_A_Number     Sensor_Group_A_Number       0x8065     FreqA_factor     Driver frequency double frequency coefficient of Driver group A GroupA_Frequence =Multiplier factor *baseband       0x8066     FreqB_factor     Driver frequency double frequency coefficient of Driver group B GroupB_Frequence =Multiplier factor *baseband       0x8067     Pannel_BitFreqL     Baseband of Driver group A\B(1526Hz <baseband<14600hz)< td="">       0x8068     Pannel_BitFreqH     Time interval of the neibouring two driving signal/Light; us)</baseband<14600hz)<>							Re	served			
0x8060   NC   Reserved     0x8061   NC   Reserved     0x8062   Drv_GroupA_Num   All_Driving   Reserved   Driver_Group_A_number     0x8063   Drv_GroupB_Num   Reserved   D_Freq   Driver_Group_B_number     0x8064   Sensor_Num   Sensor_Group_B_Number   Sensor_Group_A_Number   Sensor_Group_A_Number     0x8064   Sensor_Num   Sensor_Group_B_Number   Sensor_Group_A_Number   Sensor_Group_A_Number     0x8065   FreqA_factor   Driver frequency double frequency coefficient of Driver group A GroupA_Frequence =Multiplier factor *baseband     0x8066   FreqB_factor   Driver frequency double frequency coefficient of Driver group B GroupB_Frequence =Multiplier factor *baseband     0x8067   Pannel_BitFreqL 0x8068   Baseband of Driver group A\B(1526Hz <baseband<14600hz)< td="">     0x8069   Pannel_Sensor_TimeL   Time interval of the neibouring two driving signal/Light; us)</baseband<14600hz)<>											
0x8061     NC     Reserved       0x8062     Drv_GroupA_Num     All_Driving     Reserved     Driver_Group_A_number       0x8063     Drv_GroupB_Num     Reserved     D_Freq     Driver_Group_B_number       0x8064     Sensor_Num     Sensor_Group_B_Number     Sensor_Group_A_Number     Sensor_Group_A_Number       0x8065     FreqA_factor     Driver frequency double frequency coefficient of Driver group A GroupA_Frequence =Multiplier factor *baseband       0x8066     FreqB_factor     Driver frequency double frequency coefficient of Driver group B GroupB_Frequence =Multiplier factor *baseband       0x8067     Pannel_BitFreqL     Baseband of Driver group A\B(1526Hz Driver group A\B(1526Hz baseband<14600Hz)											
0x8062   Drv_GroupA_Num   All_Driving   Reserved   Driver_Group_A_number     0x8063   Drv_GroupB_Num   Reserved   D_Freq   Driver_Group_B_number     0x8064   Sensor_Num   Sensor_Group_B_Number   Sensor_Group_A_Number     0x8065   FreqA_factor   Driver frequency double frequency coefficient of Driver group A GroupA_Frequence =Multiplier factor *baseband     0x8066   FreqB_factor   Driver frequency double frequency coefficient of Driver group B GroupB_Frequence =Multiplier factor *baseband     0x8067   Pannel_BitFreqL   Baseband of Driver group A\B(1526Hz <baseband<14600hz)< td="">     0x8069   Pannel_Sensor_TimeL   Time interval of the neibouring two driving signal/Light; us)</baseband<14600hz)<>											
0x8063   Drv_GroupB_Num   Reserved   D_Freq   Driver_Group_B_number     0x8064   Sensor_Num   Sensor_Group_B_Number   Sensor_Group_A_Number     0x8065   FreqA_factor   Driver frequency double frequency coefficient of Driver group A GroupA_Frequence =Multiplier factor *baseband     0x8066   FreqB_factor   Driver frequency double frequency coefficient of Driver group B GroupB_Frequence =Multiplier factor *baseband     0x8067   Pannel_BitFreqL   Baseband of Driver group A\B(1526Hz baseband<14600Hz)											
0x8064   Sensor_Num   Sensor_Group_B_Number   Sensor_Group_A_Number     0x8065   FreqA_factor   Driver frequency double frequency coefficient of Driver group A GroupA_Frequence =Multiplier factor *baseband     0x8066   FreqB_factor   Driver frequency double frequency coefficient of Driver group B GroupB_Frequence =Multiplier factor *baseband     0x8067   Pannel_BitFreqL   Baseband of Driver group A\B(1526Hz Baseband<14600Hz)											
0x8065 FreqA_factor Driver frequency double frequency coefficient of Driver group A GroupA_Frequence =Multiplier factor *baseband   0x8066 FreqB_factor Driver frequency double frequency coefficient of Driver group B GroupB_Frequence =Multiplier factor *baseband   0x8067 Pannel_BitFreqL Baseband of Driver group A\B(1526Hz <baseband<14600hz)< td="">   0x8069 Pannel_Sensor_TimeL Time interval of the neibouring two driving signal/Linit: us)</baseband<14600hz)<>		Drv_GroupB_Num									
0x8065   FreqA_factor   GroupA_Frequence =Multiplier factor *baseband     0x8066   FreqB_factor   Driver frequency double frequency coefficient of Driver group B GroupB_Frequence =Multiplier factor *baseband     0x8067   Pannel_BitFreqL   Baseband of Driver group A\B(1526Hz baseband<14600Hz)	0x8064	Sensor_Num									
0x8066 FreqB_factor Driver frequency double frequency coefficient of Driver group B GroupB_Frequence =Multiplier factor *baseband   0x8067 Pannel_BitFreqL Baseband of Driver group A\B(1526Hz <baseband<14600hz)< td="">   0x8068 Pannel_BitFreqH Time interval of the neibouring two driving signal/Light; us)</baseband<14600hz)<>	0x8065	FreqA_factor									
0x8067   Pannel_BitFreqL   Baseband of Driver group A\B(1526Hz <baseband<14600hz)< td="">     0x8068   Pannel_BitFreqH   Baseband of Driver group A\B(1526Hz<baseband<14600hz)< td="">     0x8069   Pannel_Sensor_TimeL   Time interval of the neibouring two driving signal/Light; us)</baseband<14600hz)<></baseband<14600hz)<>	0x8066	FreqB_factor	Driver frequency double frequency coefficient of Driver group B						er group B		
0x8068 Pannel_BitFreqH Baseband of Driver group A\B(1526HZ baseband<14600HZ)   0x8069 Pannel_Sensor_TimeL Time interval of the neibouring two driving signal/Unit; us)	0x8067	Pannel BitFregL	D								
0x8069 Pannel_Sensor_TimeL Time interval of the neibouring two driving signal/Upit: us)		I	Base	band	ot L	river gro	oup A	8(1526)	⊣z <base< td=""><td>epand&lt;1</td><td>4000HZ)</td></base<>	epand<1	4000HZ)
			- Fimel								
UX8U6A   Pannel Sensor LimeH	0x806A	Pannel Sensor TimeH						nit: us)			



0x806B	Pannel_Tx_Gain	Reserved		Drv_outpu gears	ut_R,	Panr	el_DAC_Gain
0x806C	Pannel_Rx_Gain	Pannel_PGA C	Pannel_l			el_Rx cmi	Pannel_PGA Gain
0x806D	Pannel_Dump_Shift	Reserved Magnification coefficient of ori value(The Nth power of 2)					
0x806E	Drv_Frame_Control	Reserved	Su	oFrame_I Num			peat_Num
0x806F	NC			Reserv	ed		
0x8070	NC			Reserv	ed		
0x8071	NC			Reserv	ed		
0x8072	Stylus Tx Gain	Unc	lefined(inv	alid when	stylus	priority	y=0)
0x8073	Stylus Rx Gain		lefined(inv				
0x8074	Stylus_Dump_Shift		lefined(inv				
0x8075	Stylus_Touch_Level		lefined(inv				
0x8076	Stylus_Leave_Level		lefined(inv				
0x8077	Stylus_Control		node esca				
0x8078	NC			Reserve			
0x8079	NC			Reserve			
0x807A	Freq_Hopping_Start	Frequency	hopping st		ency(U	nit: 2KH	lz,50means
0x807B	Freq_Hopping_End	Frequency I	nopping sto		ncy(Un	iit: 2KH	z,150means
0x807C	Noise Detect Tims	Detect_Stay_	Times			Confirm	Times
0x807D	Hopping_Flag	Hop_En		served			Time Out
0x807E	Hopping_Threshold	Large_Nois					
0x807F	Noise Threshold	Largo_rtoio		shold of n			
0x8080	NC		THIOC	Reserve		101	
0x8081	NC			Reserve			
0x8082	Hopping_seg1_BitFreqL	Frequency	onnina se			entral fi	equency(for
0x8083	Hopping_seg1_BitFreqH	i requeriej i	iopping oo	driver A		ondan	oquonoj(ioi
0x8084	Hopping_seg1_Factor	Frequency h	oppina sec		/	requen	cy coefficient
0x8085	Hopping_seg2_BitFreqL						requency(for
0x8086	Hopping_seg2_BitFreqH	i requeriej i	iopping oo	driver A		ondan	oquonoj(ioi
0x8087	Hopping_seg2_Factor	Frequency h	oppina sec			requen	cy coefficient
0x8088	Hopping_seg3_BitFreqL						requency(for
0x8089	Hopping_seg3_BitFreqH	· · · · · · · · · · · · · · · · · · ·		driver A			
0x808A	Hopping_seg3_Factor	Frequency h	oppina sec			requen	cy coefficient
0x808B	Hopping_seg4_BitFreqL						requency(for
0x808C	Hopping_seg4_BitFreqH	· · · · · · · · · · · · · · · · · · ·	11.13.50	driver A			
0x808D	Hopping_seg4_Factor	Frequency h	oppina sec		/	requen	cy coefficient
0x808E	Hopping_seg5_BitFreqL						requency(for
					/B)		
0x808F	Hopping_seg5_BitFreqH		onnina sea	driver A		regues	
0x808F 0x8090	Hopping_seg5_BitFreqH Hopping_seg5_Factor		opping seç	driver A ment 5 c	entral f	requen	cy coefficient
0x808F 0x8090 0x8091	Hopping_seg5_BitFreqH Hopping_seg5_Factor NC		opping sec	driver A ment 5 c Reserve	entral f ed	requen	
0x808F 0x8090 0x8091 0x8092	Hopping_seg5_BitFreqH Hopping_seg5_Factor NC NC	Frequency h		driver A ment 5 c Reserve Reserve	entral f ed ed		cy coefficient
0x808F 0x8090 0x8091 0x8092 0x8093	Hopping_seg5_BitFreqH Hopping_seg5_Factor NC NC Key1	Frequency h	tion: 0~25	driver A ment 5 c Reserve Reserve 5 valid(0 r when 4 c	entral f ed ed means of the k	no touc	
0x808F 0x8090 0x8091 0x8092 0x8093 0x8094	Hopping_seg5_BitFreqH Hopping_seg5_Factor NC NC Key1 Key2	Frequency h	tion: 0~255 touch key	driver A gment 5 c Reserve Reserve valid(0 r when 4 c Key 2 pos	entral f ed ed means of the k sition	no touc	cy coefficient
0x808F 0x8090 0x8091 0x8092 0x8093 0x8094 0x8095	Hopping_seg5_BitFreqH Hopping_seg5_Factor NC NC Key1 Key2 Key3	Frequency h	tion: 0~25 touch key	driver A ment 5 c Reserve 5 valid(0 r when 4 c Key 2 pos Key 3 pos	entral f ed ed means of the k sition sition	no touc	cy coefficient
0x808F 0x8090 0x8091 0x8092 0x8093 0x8094	Hopping_seg5_BitFreqH Hopping_seg5_Factor NC NC Key1 Key2	Frequency h Key 1 Posi independent	tion: 0~25 touch key I	driver A ment 5 c Reserve 5 valid(0 r when 4 c Key 2 pos Key 3 pos Key 4 pos	entral f ed ed means of the k sition sition	no touc eys are	cy coefficient ch, it means 8 multiples)
0x808F 0x8090 0x8091 0x8092 0x8093 0x8094 0x8095	Hopping_seg5_BitFreqH Hopping_seg5_Factor NC NC Key1 Key2 Key3	Frequency h Key 1 Posi independent	tion: 0~25 touch key I I I it for long 1~16s)	driver A ment 5 c Reserve 5 valid(0 r when 4 c Key 2 pos Key 3 pos Key 4 pos	entral f ed means of the k sition sition sition Touch	no touc eys are valid in 0~15	cy coefficient ch, it means 8 multiples) terval setting:



0x8099	Key_Leave_Level	·	Key threshold	of touch k	еу		
0x809A	Key_Sens	KeySens_1(sen	sitivity coefficie ame below)	nt of key	KeySens_2		
0x809B	Key_Sens	KeySen		ł	KeySens_4		
0x809C	Key Restrain	Reserved Reserved					
0x809D	NC		Rese	rved			
0x809E	NC		Rese				
0x809F	NC		Rese				
0x80A0	NC		Rese				
0x80A1	NC		Rese				
0x80A2	Proximity_Drv_Select	Drv_Start_Ch(ه driving d	start channel of lirection)	D	rv_End_Ch(End channel)		
0x80A3	Proximity_Sens_Select	Sens_Start_Ch( sensing c	direction)		ens_End_Ch(End channel)		
0x80A4	Proximity_Touch_Level		oximity effective				
0x80A5	Proximity_Leave_Level		ximity ineffectiv				
0x80A6	Proximity_Freq_Factor	Frequency	mollification of p	proximity s	ensing channel		
0x80A7	Proximity_BitFreqL	Base fre	equency of prox	imitv sensi	ing channel		
0x80A8	Proximity_BitFreqH	Base frequency of proximity sensing channel					
0x80A9	Proximity_Sensor_TimeL						
0x80AA	Proximity_Sensor_Time H	Time interval			ent driving signal		
0x80AB	Proximity_Tx_Gain	Driving gain of proximity					
0x80AC	Proximity_Rx_Gain		Driving gain				
0x80AD	Proximity_Dump_Shift	Reserved			of proximity original power of 2)		
0x80AE	NC		Rese	rved			
0x80AF	NC		Rese	rved			
0x80B0	NC		Rese	rved			
0x80B1	NC		Rese	rved			
0x80B2	NC		Rese	rved			
0x80B3	NC		Rese				
0x80B4	NC		Rese				
0x80B5	NC		Rese				
0x80B6	NC		Rese	rved			
0x80B7~	Sensor_CH0~	Corres	sponding chann	el no. of IT	O Sensor		
0x80C4	Sensor_CH13						
0x80C5~ 0x80D4	NC	Reserved					
0x80D5~	Driver_CH1~	Correc	sponding chann	el no of IT			
0x80EA	Driver_CH21						
0x80EB~	NC	Reserved					
0x80FE							
0x80FF	Config_Chksum						
0x8100	Config_Fresh	Updat	ted configuration	n(by maste	er control)		



## c) Coordinates Information

Addr	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0
0x8140	DILI	DILO			Byte, ASCII		DILI	DILU
0x8140 0x8141					yte, ASCII c			
0x8141 0x8142					Byte, ASCII C			
0x8142 0x8143					Byte, ASCII			
					byte1)(Low			
0x8144								
0x8145					byte2)(High			
0x8146		x coordir			te)(current o		iulion)	
0x8147					lution(high l			
0x8148					plution(low b			
0x8149					lution(high l			
0x814A		VE	endor_id(cur		ule choice ir	normation)		
0x814B				Rese				
0x814C					(Reserved)			
0x814D	h		ges	sture value	e(Reserved)			
0x814E	buffer status	Large detect	Proximity		HaveKey	num	nber of touc	h points
0x814F			• •	trac				
0x8150					nate(low by			
0x8151					nate(high by			
0x8152					nate(low by			
0x8153					nate(high by	rte)		
0x8154		point 1 size(low byte)						
0x8155			рс		(high byte)			
0x8156		Reserved						
0x8157		track id						
0x8158	point 2 x coordinate(low byte)							
0x8159	point 2 x coordinate(high byte)							
0x815A	point 2 y coordinate(low byte)							
0x815B	point 2 y coordinate(high byte)							
0x815C	point 2 size(low byte)							
0x815D	point 2 size(high byte)							
0x815E	Reserved track id							
0x815F								
0x8160	point 3 x coordinate(low byte)							
0x8161	point 3 x coordinate(high byte)							
0x8162	point 3 y coordinate(low byte)							
0x8163	point 3 y coordinate(high byte)							
0x8164		point 3 size(low byte)						
0x8165	point 3 size(high byte)							
0x8166	Reserved							
0x8167		track id						
0x8168	point 4 x coordinate(low byte)							
0x8169	point 4 x coordinate(high byte)							
0x816A	point 4 y coordinate(low byte)							
0x816B	point 4 y coordinate(high byte)							
0x816C	point 4 size(low byte)							
0x816D	point 4 size(high byte)							
0x816E	Reserved							
0x816F		track id						
0x8170		point 5 x coordinate(low byte)						
0x8171		point 5 x coordinate(high byte)						
0x8172		point 5 y coordinate(low byte)						



0x8173	point 5 y coordinate(high byte)			
0x8174	point 5 size(low byte)			
0x8175	point 5 size(high byte)			
0x8176	Reserved			
0x8177	track id			
0x8178	point 6 x coordinate(low byte)			
0x8179	point 6 x coordinate(high byte)			
0x817A	point 6 y coordinate(low byte)			
0x817B	point 6 y coordinate(high byte)			
0x817C	point 6 size(low byte)			
0x817D	point 6 size(high byte)			
0x817E	Reserved			
0x817F	track id			
0x8180	point 7 x coordinate(low byte)			
0x8181	point 7 x coordinate(high byte)			
0x8182	point 7 y coordinate(low byte)			
0x8183	point 7 y coordinate(high byte)			
0x8184	point 7 size(low byte)			
0x8185	point 7 size(high byte)			
0x8186	Reserved			
0x8187	track id			
0x8188	point 8 x coordinate(low byte)			
0x8189	point 8 x coordinate(low byte)			
0x818A	point 8 y coordinate(lingh byte)			
0x818B	point 8 y coordinate(low byte)			
0x818C	point 8 size(low byte)			
0x818D	point 8 size(high byte)			
0x818E	Reserved			
0x818F	track id			
0x8190	point 9 x coordinate(low byte)			
0x8191	point 9 x coordinate(high byte)			
0x8192	point 9 y coordinate(low byte)			
0x8193	point 9 y coordinate(high byte)			
0x8194	point 9 size(low byte)			
0x8195	point 9 size(high byte)			
0x8196	Reserved			
0x8197	track id			
0x8198	point 10 x coordinate(low byte)			
0x8199	point 10 x coordinate(high byte)			
0x819A	point 10 y coordinate(low byte)			
0x819B	point 10 y coordinate(high byte)			
0x819C	point 10 size(low byte)			
0x819D	point 10 size(high byte)			
0x819E	Reserved			
0x819F	Keyvaule			



## **RELIABILITY TEST**

No.	Test Item	Test Condition		
1	High Temperature Storage	$80\pm2^{\circ}C/240$ hours		
2	Low Temperature Storage	$-30\pm2^{\circ}C/240$ hours		
3	High Temperature Operating	$70\pm2^{\circ}C/240$ hours		
4	Low Temperature Operating	$-20\pm2^{\circ}C/240$ hours		
5	Temperature Cycle storage	$-30\pm2^{\circ}C\sim25\sim80\pm2^{\circ}C\times200$ cycles (30min.) (5min.) (30min.)		
6	Damp proof Test operating	$60^{\circ}\text{C} \pm 5^{\circ}\text{C} \times 90\%$ RH/240 hours		
7	Vibration Test (no-operation)	Frequency: 0~55Hz Amplitude:1.5mm Sweep time: 11min 6 cycles for each direction of X.Y.Z		
8	ESD test (No operation)	150pF,330Ω Air: ± 12KV;Contact: ± 6KV 10 time/point;4 point/panel face		



## ■ INSPECTION CRITERION

MI	OUTGOING QUALITY STANDARD	PAGE 1 OF 3				
TITLE:FUNCTIO	TITLE:FUNCTIONAL TEST & INSPECTION CRITERIA					
This specification is made to be used as the standard acceptance/rejection criteria for Wider						

Screen TFT-LCD module product.

## 1. Sample plan

Sampling plan according to GB/T2828.1-2003/ISO 2859-1: 1999 and ANSI/ASQC Z1.4-1993, normal level 2 and based on:

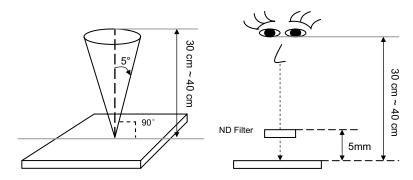
Major defect: AQL 0.65

Minor defect: AQL 1.5

#### 2. Inspection condition

1.1 Inspection conditions

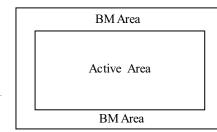
- 1.1.1 Inspection Distance :  $35 \pm 5$ cm
- 1.1.2 View Angle :
  - (1) Inspection under operating condition :  $\pm 5^{\circ}$
  - (2) Inspection under non-operating condition :  $\pm 45^{\circ}$



1.1.3 Environment conditions :

Ambien	t Temperature :	25± 5℃	
Ambi	ent Humidity :	$65\pm5\%$	
Ambient Illumination	Cosmetic Inspection	More than 600lux	
	Functional Inspection	300 ~ 800lux	

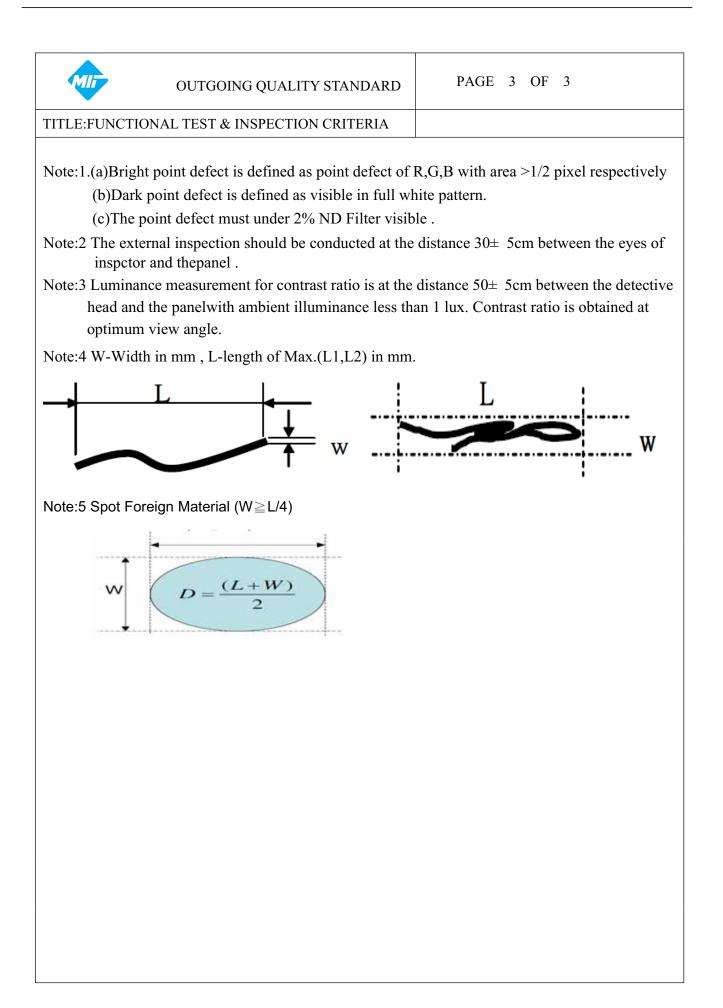
1.2 Definition of applicable Zones





MIF	OUTGOIN	IG QUALITY STAI	NDARD	PAG	GE 2 OF	3	
LE:FUN	CTIONAL TEST & I	NSPECTION CRIT	TERIA				
Inspec	tion parameters						
No.	Parameter	Criteria					
		Display function: No	o Display m	alfunction (N	(Iajor)		
		Contrast ratio (Black, White):					
		Does not meet specified range in the spec. (Major) (Note:3)					
		Line Defect: No obvious Vertical and Horizontal line defect in bright, dark					
		and colored. (Major) (Note:1) Point Defect (Red, green, blue, dark): Active area ≤5dots (Minor)(Note:1)					
		Point Defect (Red, g	reen, blue, o	dark): Active	area ≤5dots (	Minor)(Note:1)	
			Acceptable		Class Of	AQL	
		Item	number	Total	Defects	Level	
		Bright	3	8			
		Dark Adjacent Bright	5	1	Minor	1.5	
		Adjacent Dark	2	2			
				11			
		Non-uniformity:					
1	Operating	Visible through 6%N					
		Foreign material in Black or White spots shape (W>1/4L) (Note: 5)					
		D: .		Acceptable	Class Of	AQL	
		Dimension		number	Defects	Level	
		D ≤ 0.3		*		1.5	
		$\begin{array}{ c c c c c c c c c c c c c c c c c c c$		4	Minor	Minor 1.5	
		D = (Long + Short) / 2 * : Disregard					
		Foreign Material in Line or spiral shape (W≤1/4L) (Note: 4)					
			I				
		Dimensio	on	Acceptable	e Class Of Defects	AQL Level	
		W>0.1mm,L>5mm	1	number 0	Delects	Levei	
		L≦5mm,0.05mm<	$W \leq 0.1 mm$	4	Minor	1.5	
		$\[ L \leq 5 \text{mm}, W < 0.05 \text{mm} \] * \]$					
		L: Length W: Width *: Disregard					
		Dimension: Outline	(Maior)				
		Bezel appearance: uneven (Minor)					
		Scratch on the polarize & TP: (Note:2)					
		Dimonsi	<b>on</b>	Acceptab	le Class Of	AQL	
		Dimensi		number	· Defects	Level	
		W>0.1mm,L>10mm L≤10mm,0.05mm		$\begin{array}{c c} 0\\ n & 4 \end{array}$	Minor	1.5	
2	External Inspection (non-operating)	$L \leq 10$ mm, $0.03$ mm $L \leq 10$ mm, $W < 0.05$		<u>11 4</u> *		1.3	
2		L : Length W : Width * : Disregard					
		Dent and spots shape on the polarize & TP (Note:2): (Note: 5)					
				A coortal-1			
		Dimensio	on	Acceptabl number	e Class Of Defects	AQL Level	
		D ≤ 0.3		*			
		0.3 < D ≤0.8		4	Minor	1.5	
		D>0.8		0			
		D = (Long + Short)	/2 *:Dis	sregard			







## **PRECAUTIONS FOR USING LCD MODULES**

#### **Handing Precautions**

(1) The display panel is made of glass and polarizer. As glass is fragile. It tends to become or chipped during handling especially on the edges. Please avoid dropping or jarring. Do not subject it to a mechanical shock by dropping it or impact.

(2) If the display panel is damaged and the liquid crystal substance leaks out, be sure not to get any in your mouth. If the substance contacts your skin or clothes, wash it off using soap and water.

(3) Do not apply excessive force to the display surface or the adjoining areas since this may cause the color tone to vary. Do not touch the display with bare hands. This will stain the display area and degraded insulation between terminals (some cosmetics are determined to the polarizer).

(4) The polarizer covering the display surface of the LCD module is soft and easily scratched. Handle this polarizer carefully. Do not touch, push or rub the exposed polarizers with anything harder than an HB pencil lead (glass, tweezers, etc.). Do not put or attach anything on the display area to avoid leaving marks on. Condensation on the surface and contact with terminals due to cold will damage, stain or dirty the polarizer. After products are tested at low temperature they must be warmed up in a container before coming is contacting with room temperature air.

(5) If the display surface becomes contaminated, breather on the surface and gently wipe it with a soft dry cloth. If it is heavily contaminated, moisten cloth with one of the following solvents

- Isopropyl alcohol

- Ethyl alcohol

Do not scrub hard to avoid damaging the display surface.

(6) Solvents other than those above-mentioned may damage the polarizer. Especially, do not use the following.

- Water

- Ketone

- Aromatic solvents

Wipe off saliva or water drops immediately, contact with water over a long period of time may cause deformation or color fading. Avoid contacting oil and fats.

(7) Exercise care to minimize corrosion of the electrode. Corrosion of the electrodes is accelerated by water droplets, moisture condensation or a current flow in a high-humidity environment.

(8) Install the LCD Module by using the mounting holes. When mounting the LCD module make sure it is free of twisting, warping and distortion. In particular, do not forcibly pull or bend the I/O cable or the backlight cable.

(9) Do not attempt to disassemble or process the LCD module.

(10) NC terminal should be open. Do not connect anything.

(11) If the logic circuit power is off, do not apply the input signals.

(12) Electro-Static Discharge Control, Since this module uses a CMOS LSI, the same careful attention should be paid to electrostatic discharge as for an ordinary CMOS IC. To prevent destruction of the elements by static electricity, be careful to maintain an optimum work environment.

- Before remove LCM from its packing case or incorporating it into a set, be sure the module and your body have the same electric potential. Be sure to ground the body when handling the LCD modules.

- Tools required for assembling, such as soldering irons, must be properly grounded. make certain the AC power source for the soldering iron does not leak. When using an electric screwdriver to attach LCM, the screwdriver should be of ground potentiality to minimize as much as possible any transmission of electromagnetic waves produced sparks coming from the commutator of the motor.

- To reduce the amount of static electricity generated, do not conduct assembling and other work under dry conditions. To reduce the generation of static electricity be careful that the air in the work is not too dried. A relative humidity of 50%-60% is recommended. As far as possible make the electric potential of your work clothes and that of the work bench the ground potential

- The LCD module is coated with a film to protect the display surface. Exercise care when peeling off this protective film since static electricity may be generated

(13) Since LCM has been assembled and adjusted with a high degree of precision, avoid applying excessive shocks to the module or making any alterations or modifications to it.

- Do not alter, modify or change the shape of the tab on the metal frame.

- Do not make extra holes on the printed circuit board, modify its shape or change the positions of components to be attached.

- Do not damage or modify the pattern writing on the printed circuit board.

- Absolutely do not modify the zebra rubber strip (conductive rubber) or heat seal connector.

- Except for soldering the interface, do not make any alterations or modifications with a soldering iron.

- Do not drop, bend or twist LCM.



#### Handling precaution for LCM

LCM is easy to be damaged. Please note below and be careful for handling. Correct handling:





As above picture, please handle with anti-static gloves around LCM edges.

#### **Incorrect handling:**



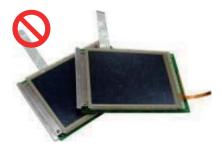
Please don't touch IC directly.



Please don't hold the surface of panel.



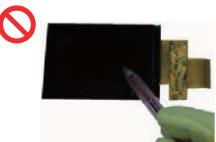
Please don't hold the surface of IC.



Please don't stack LCM.



Please don't stretch interface of output, such as FPC cable.



Please don't operate with sharp stick such as pens.



#### **Storage Precautions**

When storing the LCD modules, the following precaution is necessary.

(1) Store them in a sealed polyethylene bag. If properly sealed, there is no need for the dessicant.

(2) Store them in a dark place. Do not expose to sunlight or fluorescent light, keep the temperature between  $0^{\circ}$ C and  $35^{\circ}$ C, and keep the relative humidity between  $40^{\circ}$ RH and  $60^{\circ}$ RH.

(3) The polarizer surface should not come in contact with any other objects. (We advise you to store them in the anti-static electricity container in which they were shipped.

#### Others

Liquid crystals solidify under low temperature (below the storage temperature range) leading to defective orientation or the generation of air bubbles (black or white). Air bubbles may also be generated if the module is subject to a low temperature.

If the LCD modules have been operating for a long time showing the same display patterns, the display patterns may remain on the screen as ghost images and a slight contrast irregularity may also appear. A normal operating status can be regained by suspending use for some time. It should be noted that this phenomenon does not adversely affect performance reliability.

To minimize the performance degradation of the LCD modules resulting from destruction caused by static electricity etc., exercise care to avoid holding the following sections when handling the modules.

- Exposed area of the printed circuit board.

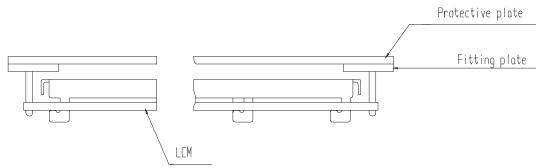
-Terminal electrode sections.

## ■ USING LCD MODULES

#### **Installing LCD Modules**

The hole in the printed circuit board is used to fix LCM as shown in the picture below. Attend to the following items when installing the LCM.

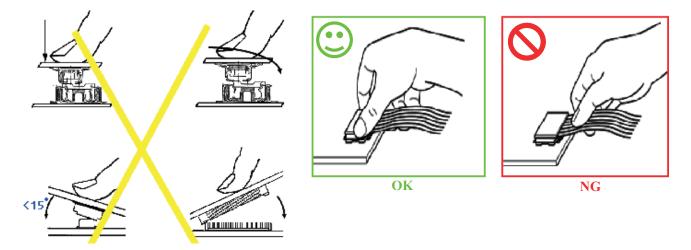
(1) Cover the surface with a transparent protective plate to protect the polarizer and LC cell.



(2) When assembling the LCM into other equipment, the spacer to the bit between the LCM and the fitting plate should have enough height to avoid causing stress to the module surface, refer to the individual specifications for measurements. The measurement tolerance should be  $\pm 0.1$  mm.

#### Precaution for assemble the module with BTB connector:

Please note the position of the male and female connector position, don't assemble or assemble like the method which the following picture shows





#### Precaution for soldering the LCM

	Manual soldering	Machine drag soldering	Machine press soldering
No ROHS	290°C ~350°C.	330°C ~350°C.	300°C ~330°C.
product	Time : 3-5S.	Speed : 4-8 mm/s.	Time : 3-6S.
product			Press: 0.8~1.2Mpa
ROHS	340°C ∼370°C.	350°C ~370°C.	330°C ~360°C.
product	Time : 3-5S.	Time : 4-8 mm/s.	Time : 3-6S.
product			Press: 0.8~1.2Mpa

(1) If soldering flux is used, be sure to remove any remaining flux after finishing to soldering operation. (This does not apply in the case of a non-halogen type of flux.) It is recommended that you protect the LCD surface with a cover during soldering to prevent any damage due to flux spatters.

(2) When soldering the electroluminescent panel and PC board, the panel and board should not be detached more than three times. This maximum number is determined by the temperature and time conditions mentioned above, though there may be some variance depending on the temperature of the soldering iron.

(3) When remove the electroluminescent panel from the PC board, be sure the solder has completely melted, the soldered pad on the PC board could be damaged.

#### **Precautions for Operation**

(1) Viewing angle varies with the change of liquid crystal driving voltage (VLCD). Adjust VLCD to show the best contrast.

(2) It is an indispensable condition to drive LCD's within the specified voltage limit since the higher voltage then the limit cause the shorter LCD life. An electrochemical reaction due to direct current causes LCD's undesirable deterioration, so that the use of direct current drive should be avoided.

(3) Response time will be extremely delayed at lower temperature than the operating temperature range and on the other hand at higher temperature LCD's show dark color in them. However those phenomena do not mean malfunction or out of order with LCD's, Which will come back in the specified operating temperature.

(4) If the display area is pushed hard during operation, the display will become abnormal. However, it will return to normal if it is turned off and then back on.

(5) A slight dew depositing on terminals is a cause for electro-chemical reaction resulting in terminal open circuit. Usage under the maximum operating temperature, 50%RH or less is required.

(6) Input logic voltage before apply analog high voltage such as LCD driving voltage when power on. Remove analog high voltage before logic voltage when power off the module. Input each signal after the positive/negative voltage becomes stable.

(7) Please keep the temperature within specified range for use and storage. Polarization degradation, bubble generation or polarizer peel-off may occur with high temperature and high humidity.

#### Safety

(1) It is recommended to crush damaged or unnecessary LCDs into pieces and wash them off with solvents such as acetone and ethanol, which should later be burned.

(2) If any liquid leaks out of a damaged glass cell and comes in contact with the hands, wash off thoroughly with soap and water.

#### Limited Warranty

Unless agreed between Multi-Inno and customer, Multi-Inno will replace or repair any of its LCD modules which are found to be functionally defective when inspected in accordance with Multi-Inno LCD acceptance standards (copies available upon request) for a period of one year from date of production Cosmetic/visual defects must be returned to Multi-Inno within 90 days of shipment Confirmation of such date shall be based on data code on product The warranty liability of Multi-Inno limited to repair and/or replacement on the terms set forth above.Multi-Inno will not be responsible for any subsequent or copse uential events.

#### **Return LCM under warranty**

No warranty can be granted if the precautions stated above have been disregarded. The typical examples of violations are :

- Broken LCD glass.
- PCB eyelet is damaged or modified.
- PCB conductors damaged.
- Circuit modified in any way, including addition of components.
- PCB tampered with by grinding, engraving or painting varnish.
- Soldering to or modifying the bezel in any manner.



Module repairs will be invoiced to the customer upon mutual agreement. Modules must be returned with sufficient description of the failures or defects. Any connectors or cable installed by the customer must be removed completely without damaging the PCB eyelet, conductors and terminals.

## PRIOR CONSULT MATTER

- 1. (1) For Multi-Inno standard products, we keep the right to change material, process ... for improving the product property without notice on our customer.
- <sup>(2)</sup>For OEM products, if any change needed which may affect the product property, we will consult with our customer in advance.
- 2.If you have special requirement about reliability condition, please let us know before you start the test on our samples.